

ESA's Earth Explorer BIOMASS Workshop
XVII (17) EEBIOMASS Special Session

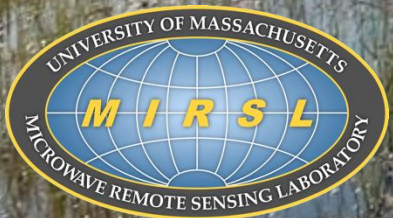
NISAR for Ecosystems

14:05 – 14:35 CET

Paul Siqueira

Microwave Remote
Sensing Laboratory

Univ. of Massachusetts
Caltech, Geological and
Planetary Sciences (GPS)





Ecosystem Science with NISAR



Paul Siqueira
Lead NISAR Ecosystems
Science Team

UMass /Amherst

Ralph Dubayah,
John Armston UMD

Bruce Chapman,
Sassan Saatchi,
Alex Christensen,
KC Cushman,
Erika Podest, JPL

Anup Das,
Chakrapani Patnaik,
ISRO

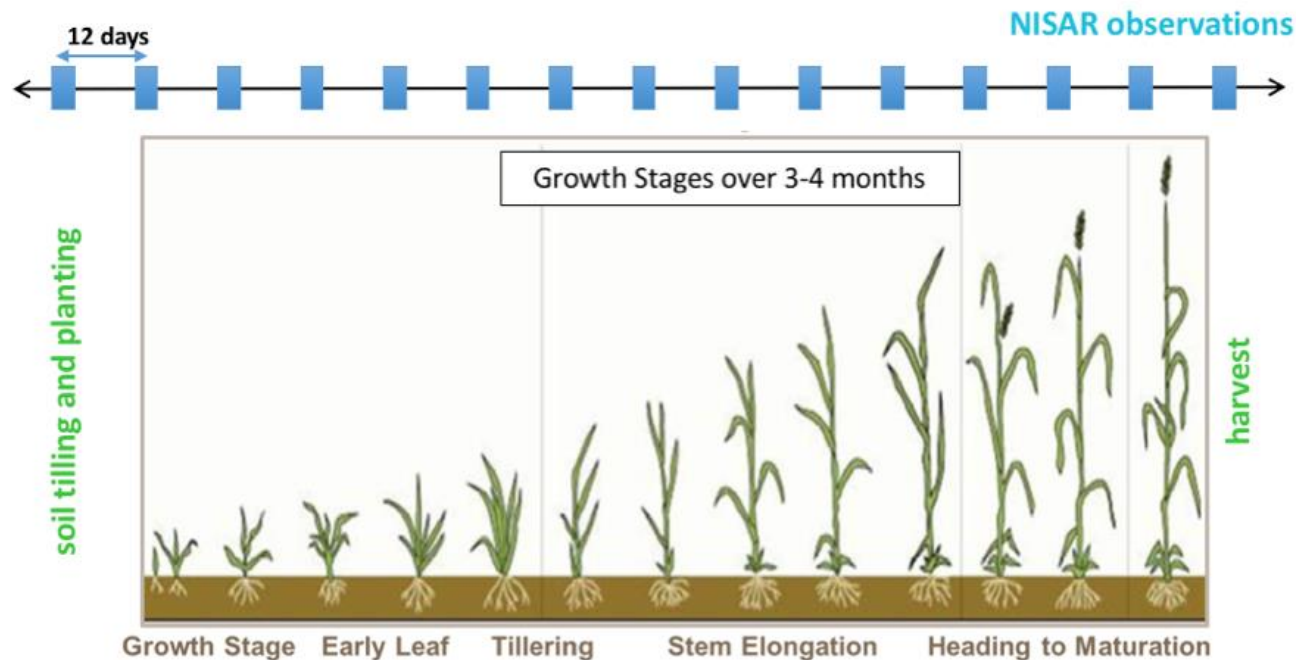
Josef Kellndorfer,
Earth Big Data

Kyle McDonald,
Nick Steiner CCNY

Narayanarao
Bhogapurapu,
UMass

- Biomass
- Disturbance
- Inundation
- Agriculture

Dense-time series of L-band data (dual-pol)



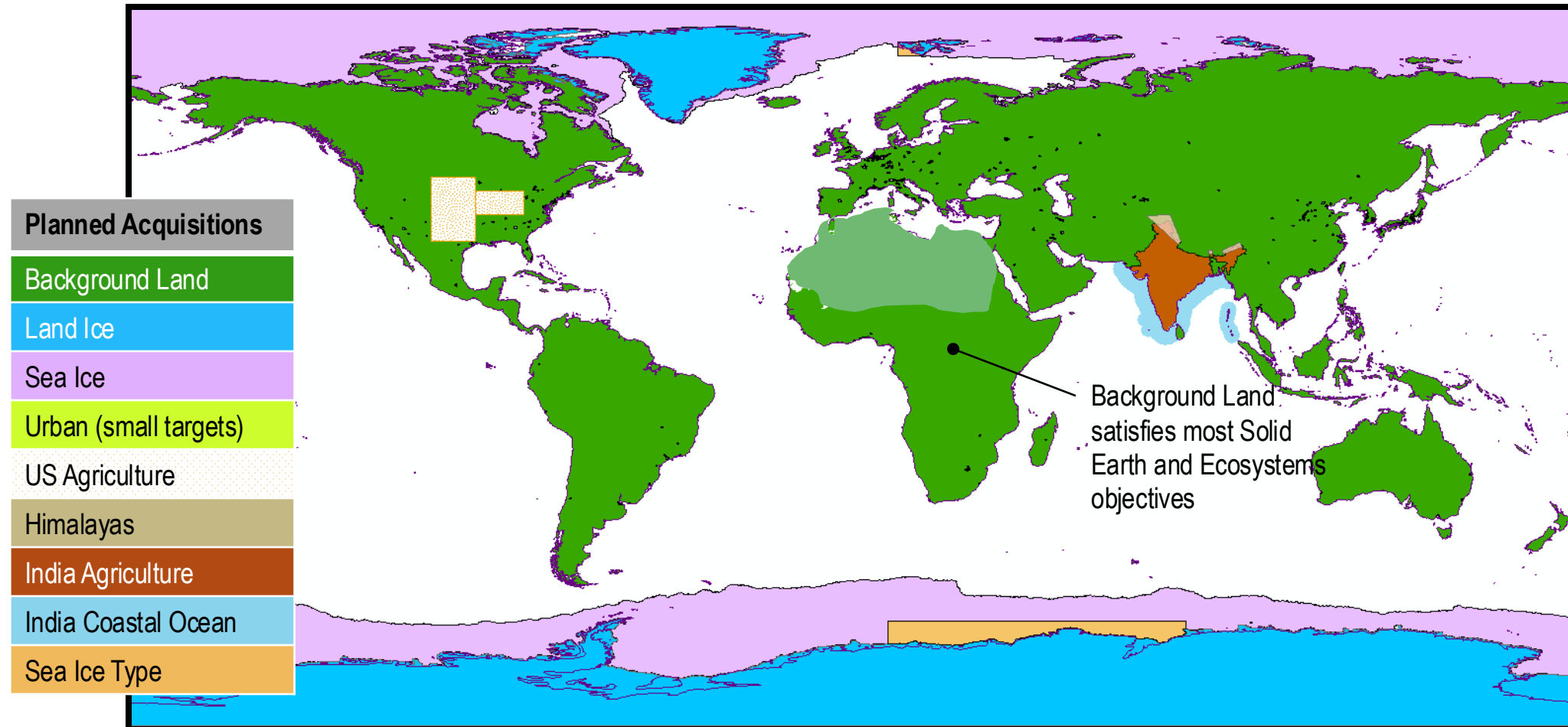
NISAR is in its final stages of integration and test!



- Ecosystems
 - Vegetation: Forests, Agriculture, Woody encroachment & Desertification
 - Biodiversity: Forests as a biomarker for habitats
 - Ecosystems services: O₂, water purification, fire control, resources
 - Marker of change in our environment
- Driven by the water cycle
- Structural components span the range of centimeters to meters
- Global in extent
- Vertical structure, horizontal distribution, complexity of living organisms
 - Dual- and Quad-polarization are interesting tools to explore

Mode-Specific Science Targets in Observation Plan

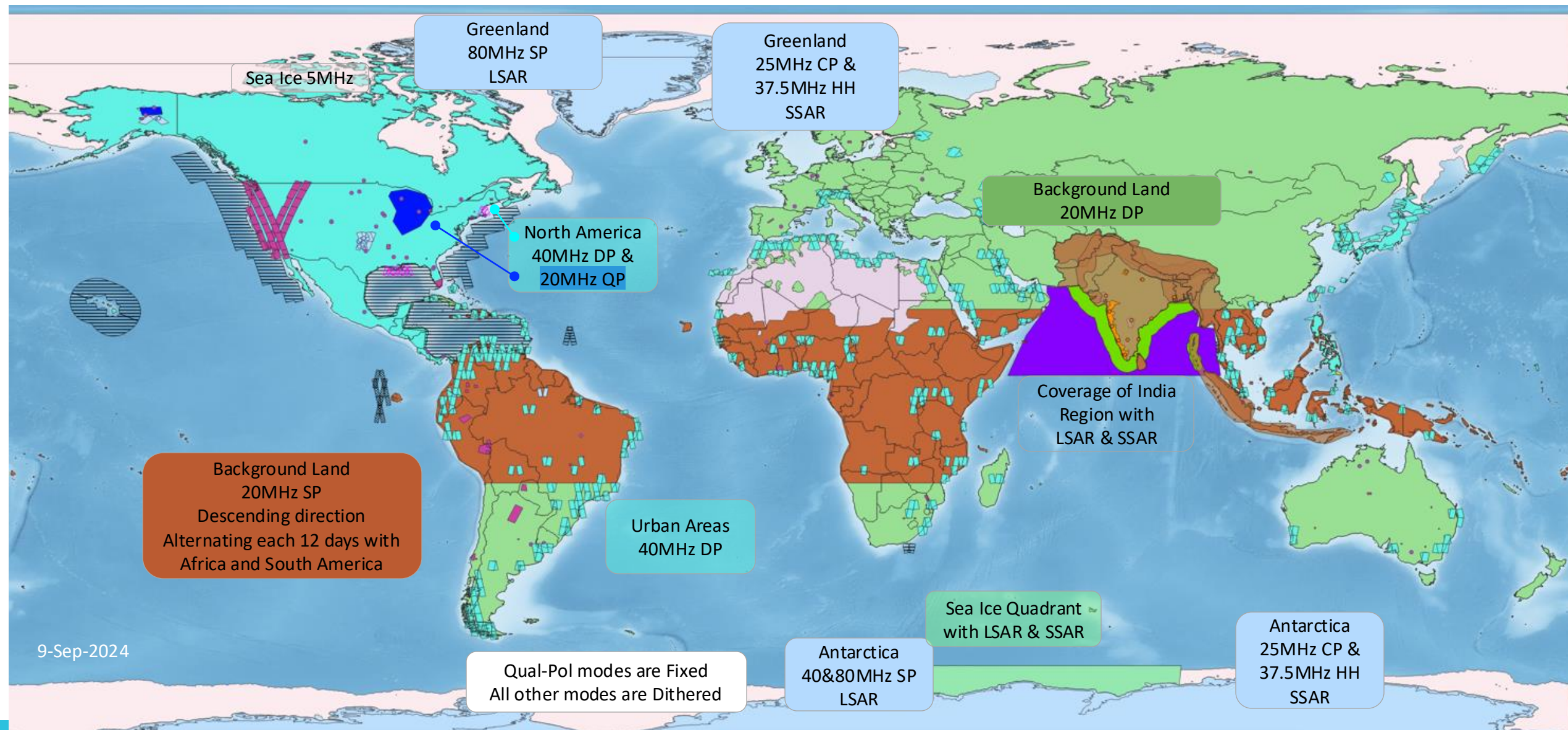
- Each colored region represents a single radar mode chosen to satisfy multiple science objectives over that area.
- Avoids mode contention that would interrupt time series



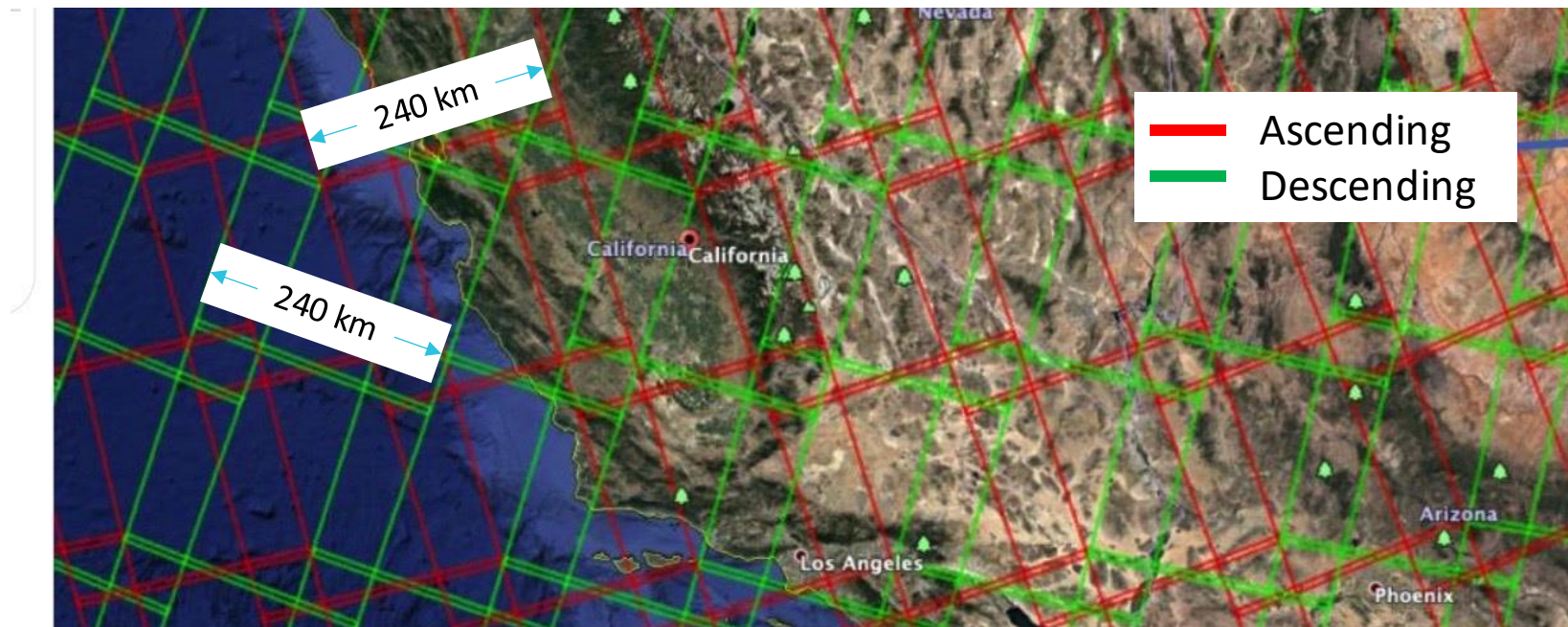
US-Quad-pol collection over the states of Illinois, Michigan, Ohio, and parts of Alaska.

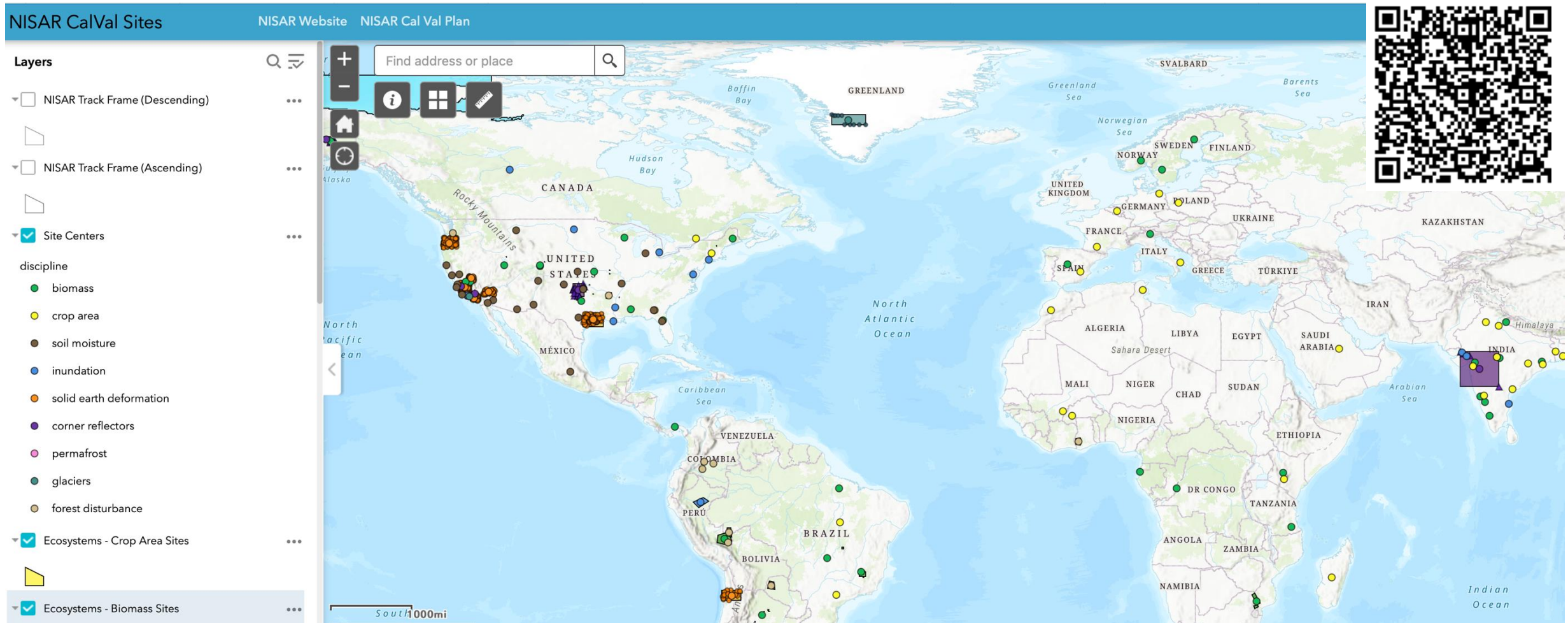


More detailed mode coverage



- Data are planned to be collected in track/frame coordinate system
- 173 unique tracks that comprehensively span the equator
- Within a single track/frame, data collection mode will be uniform, at the lowest bandwidth
- Higher bandwidth segments delivered separately





- Use the QR code above to go to the website that shows the track/frames and different cal/val sites

NISAR Mission Observation Plan

This map provides an overview of the NISAR radar observation plan. The observation plan displayed here is gridded by "Track (orbit)/Frame (latitude band)" defined by the image swaths of the 12 day repeat orbit of NISAR, but each Track/Frame may be composed of data collected in multiple radar modes. Sometimes the mode(s) of a Track/Frame may vary periodically during the mission.

Red Track/Frames indicate that the same radar observation mode in this track/frame will not change during the first 3 years of the NISAR mission.

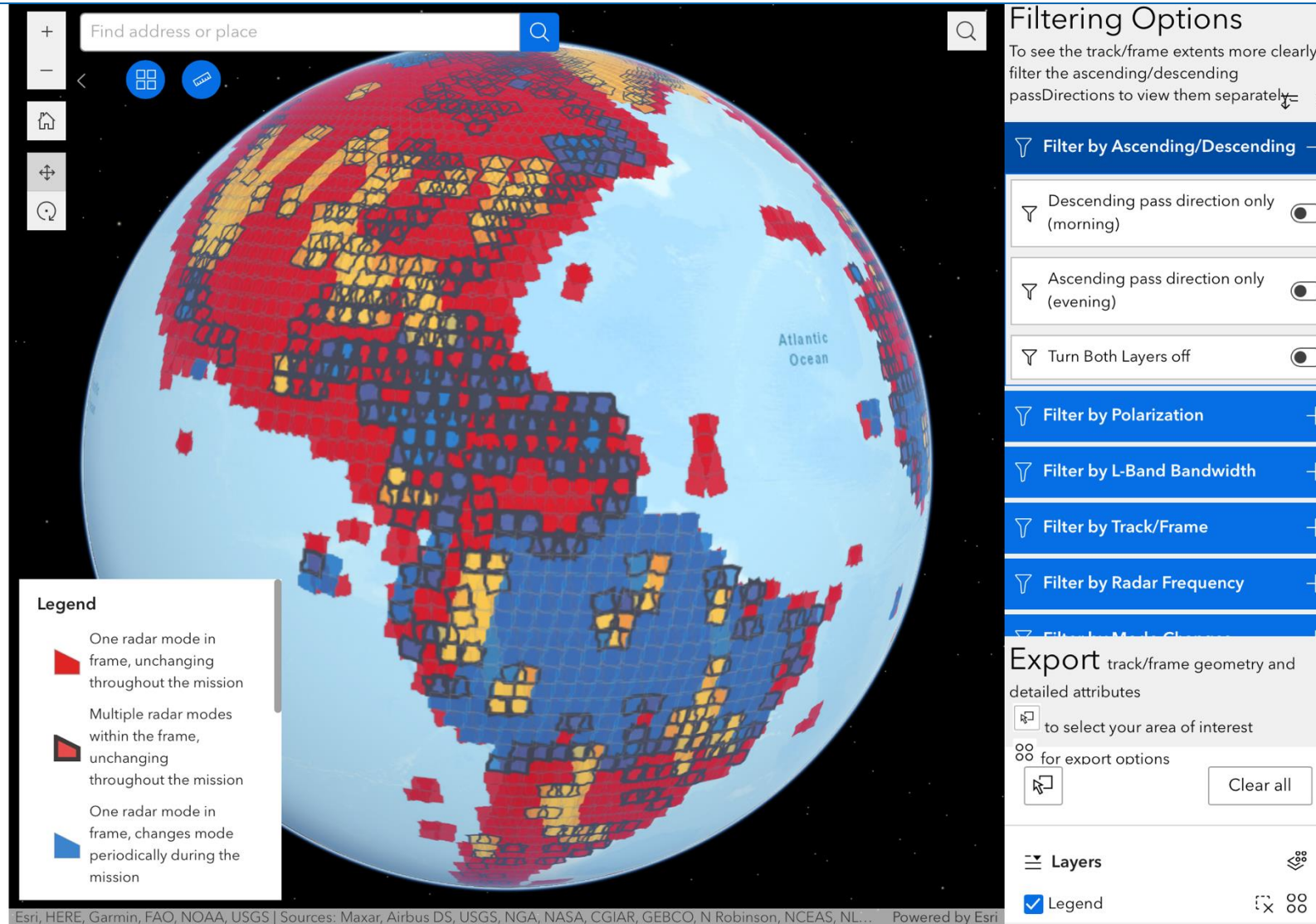
Blue Track/Frames indicate that the radar observation mode in this track/frame will periodically change over time.

Black-bordered Track/Frames indicate that multiple radar modes occur within this track/frame.

Yellow Track/Frames indicate S-Band data is collected in addition to L-Band

Note: Track/frame colors may differ slightly from the legend where ascending/descending passes overlap, due to layer transparency.

Each radar mode is identified by its frequency (L or S), followed by the bandwidth of the primary band, followed by its polarization mode; and if present, followed by the bandwidth of the secondary band, followed by its



NISAR modes and track frame can also be explored via the observing plan website.

Data can be selected and exported into different formats (JSON, etc.)

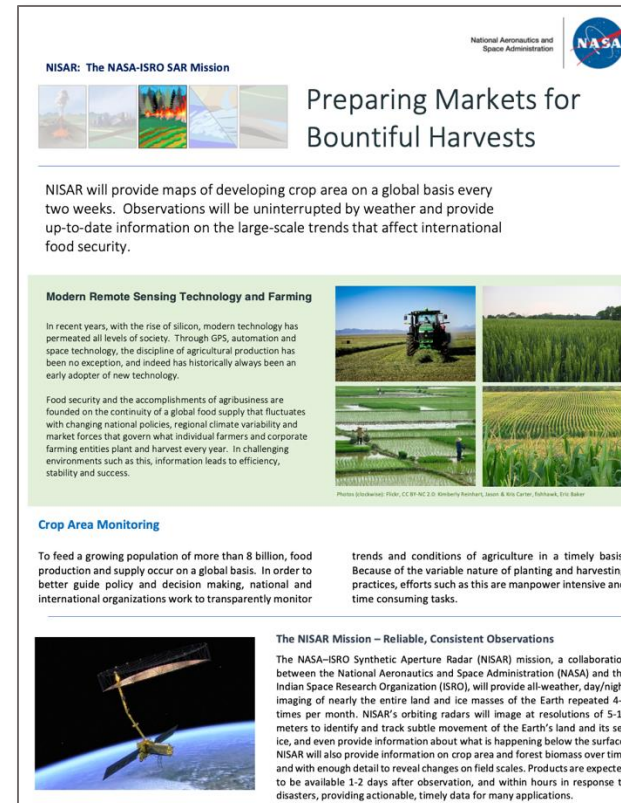
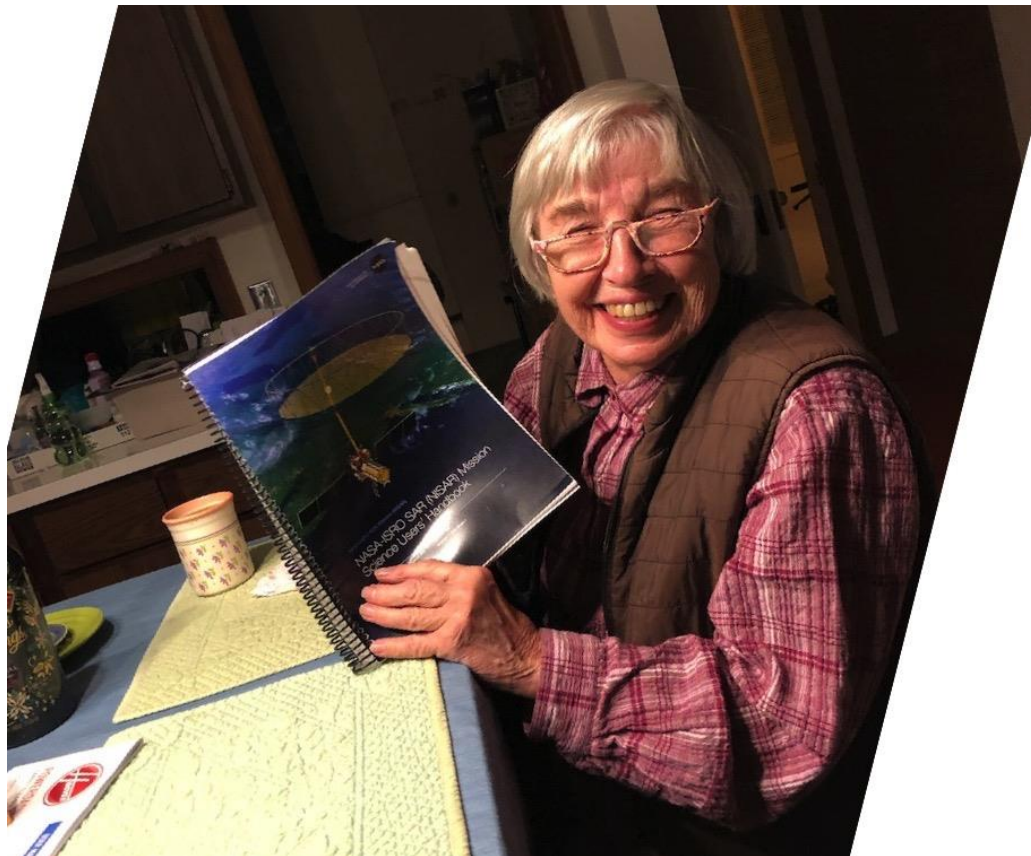


• NISAR science handbook

- Available now as a pdf (nisar.jpl.nasa.gov/getengaged/resources/)
- Being updated now

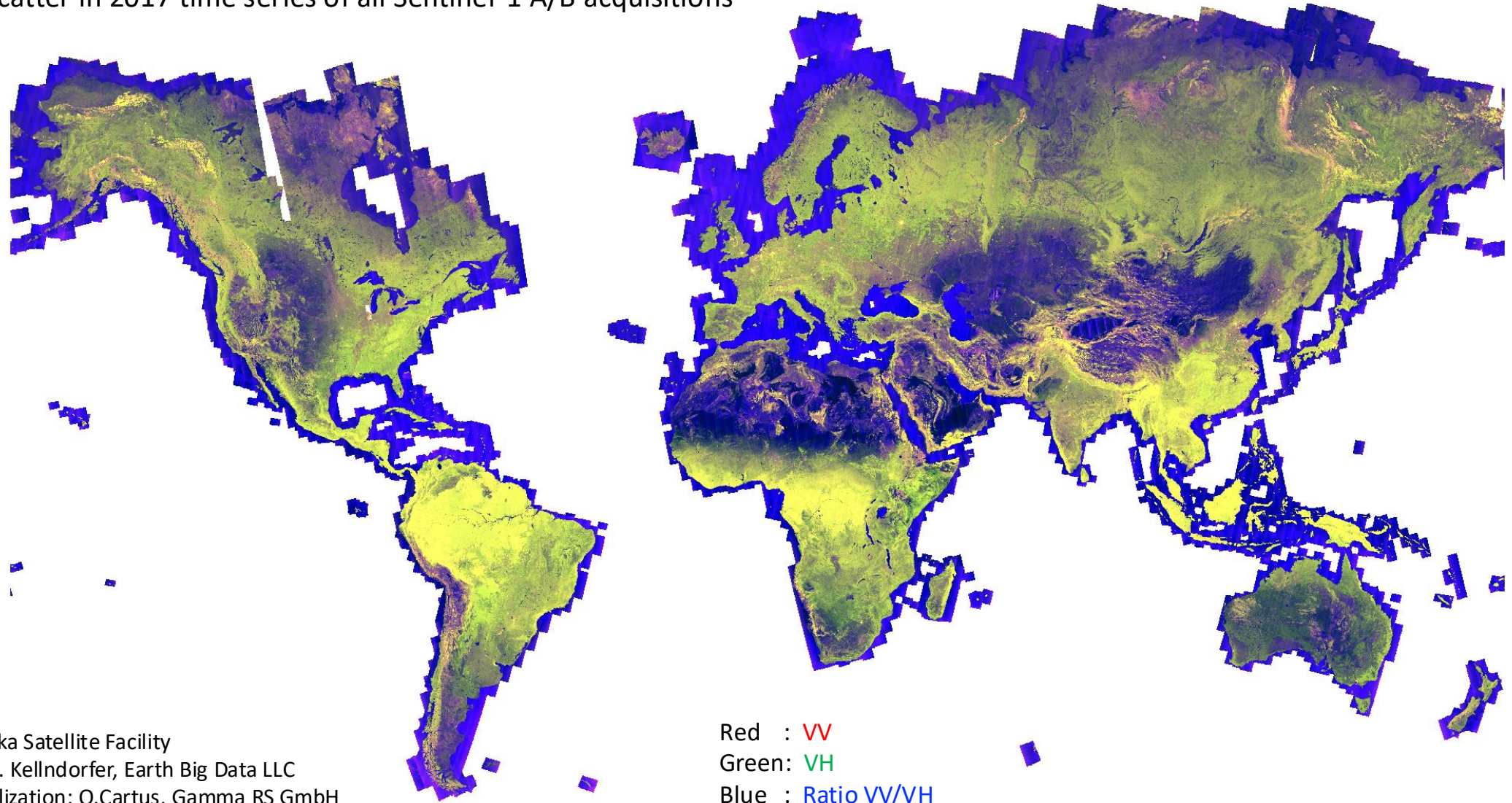
• NISAR applications white papers

- 26 one-page double sided suitable for printing flyers



2017 Sentinel-1 C-band Backscatter of Earth

Median backscatter in 2017 time series of all Sentinel-1 A/B acquisitions



Data Source: ESA/Alaska Satellite Facility
RTC Data Processing: J. Kelndorfer, Earth Big Data LLC
Mosaicking and Visualization: O.Cartus, Gamma RS GmbH



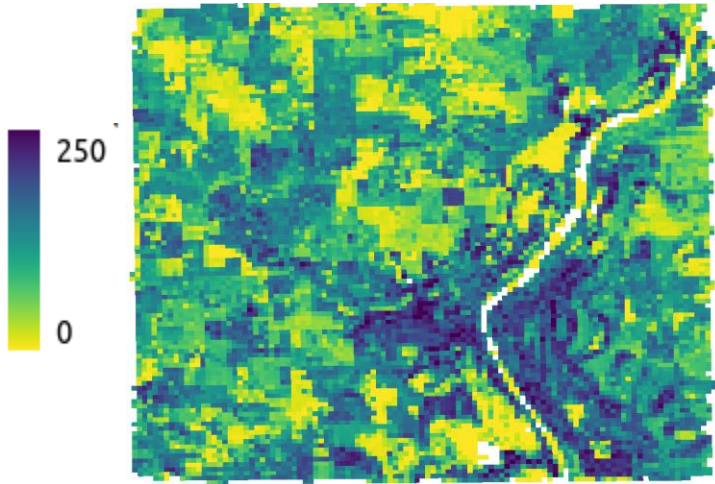
NISAR Mission at a glance

- Four Level-1 Disciplines
 - *Ecosystems/Hydrology*, • *Ice Sheets*, • *Solid Earth Dynamics*, • *Applications*
- L- & S-band 12-day orbital repeat, left-looking only mission (observations are during ascending and descending passes, so effectively two observations every 12 days)
- 240 km swath using SweepSAR
- Dominant observing mode is L-band dual-pol, 20 m multi-looked resolution. S-band collected outside of India at Cal/Val sites.
- Launch coming soon!
- 4.5 TB/day data downlink
- NISAR is a requirements driven mission.
- Example of a NISAR requirement (biomass):
 - NISAR will estimate global above ground biomass up to 100 t/ha at a 1 ha resolution, with an accuracy of 20 t/ha.
- NISAR reliable time-series observations will provide an unprecedented tool for monitoring the terrestrial environment and ecological habitats
- Data downloadable via the Alaska Satellite Facility (ASF) DAAC. Amazon Web Services (AWS) primary mechanism of getting data

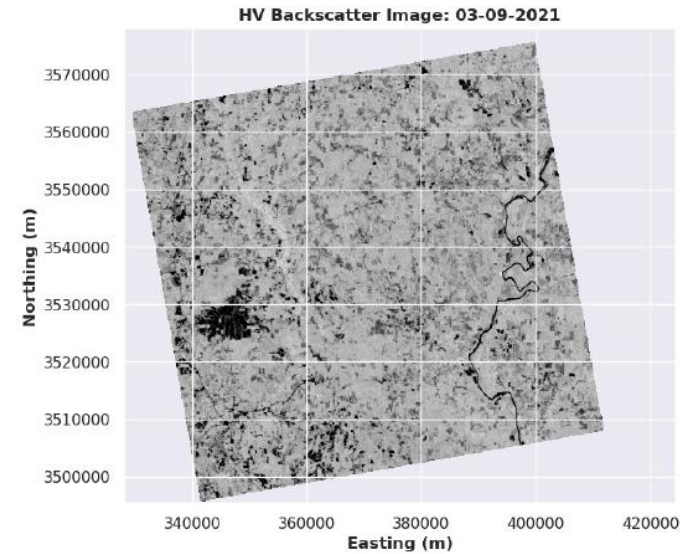
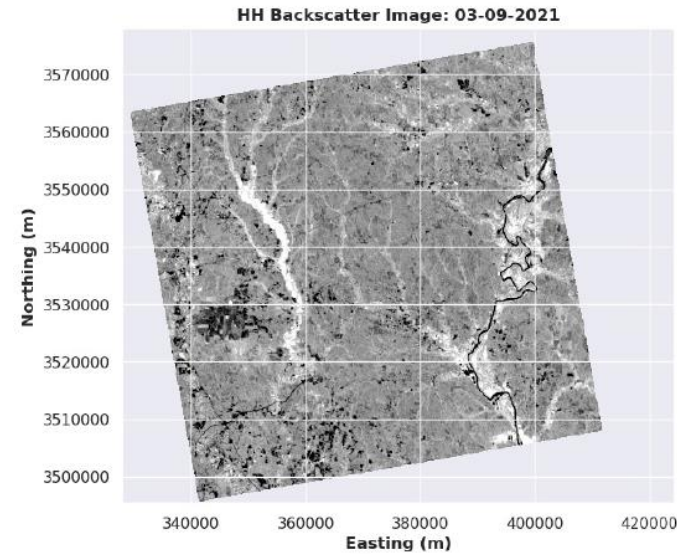


Biomass Highlights

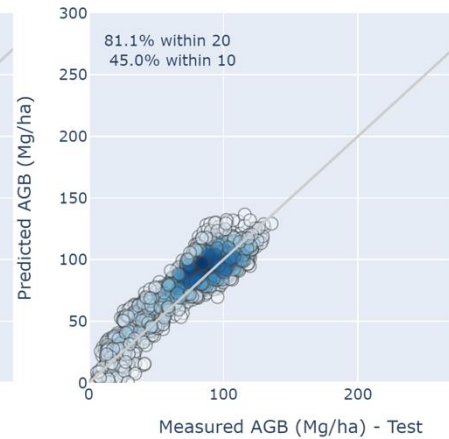
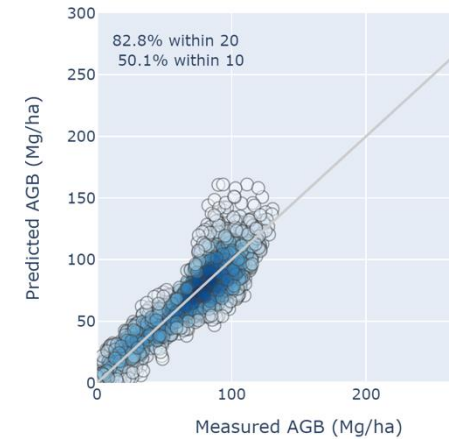
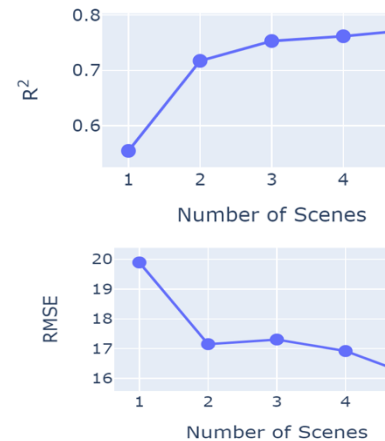
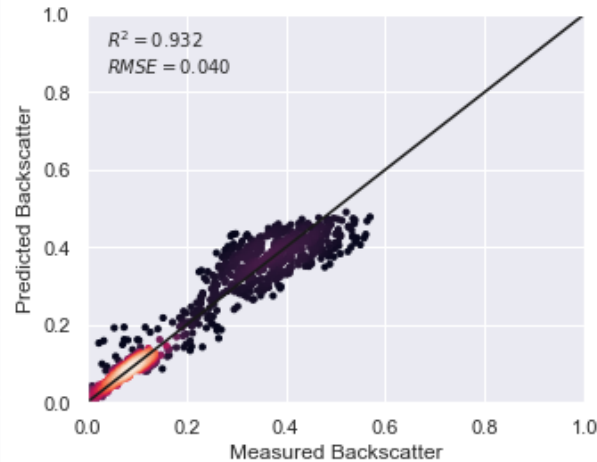
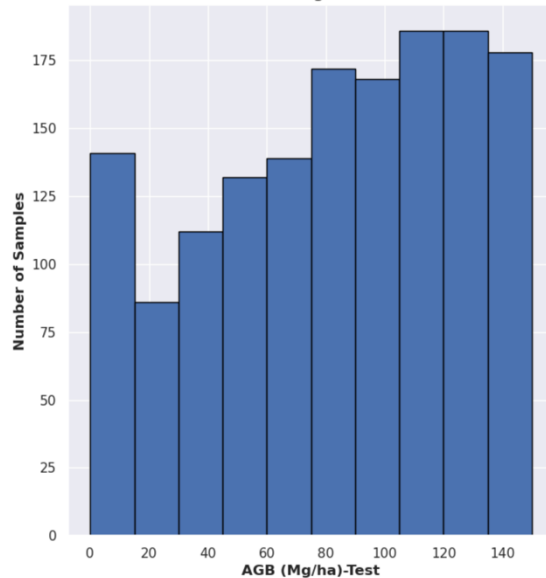
ALOS-2 over NEON site, Lenoir Landing, NC



Lenoir Landing
Aboveground
biomass
variations from
ALS data

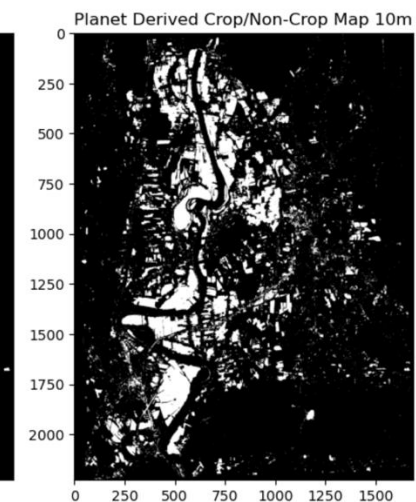
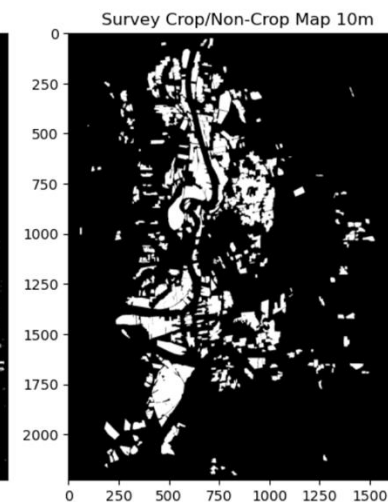
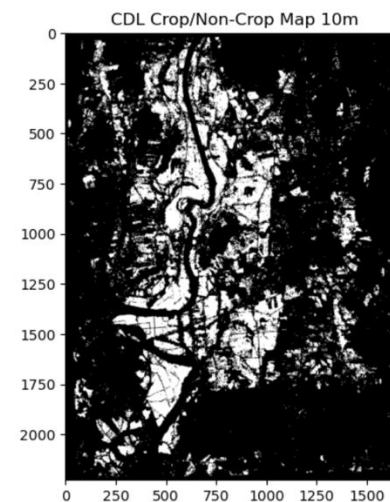
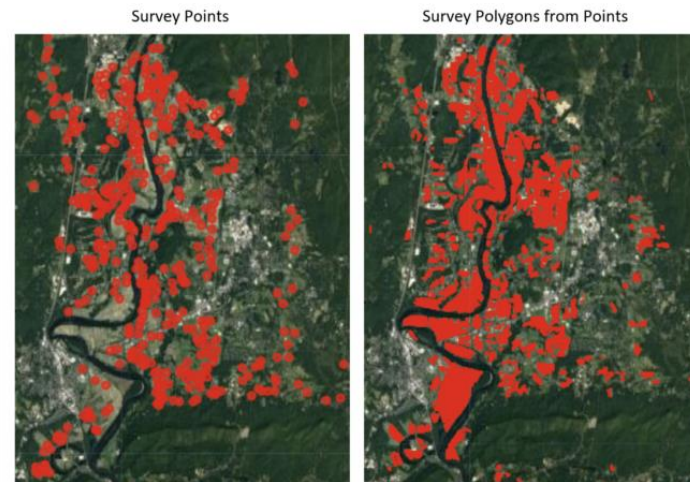
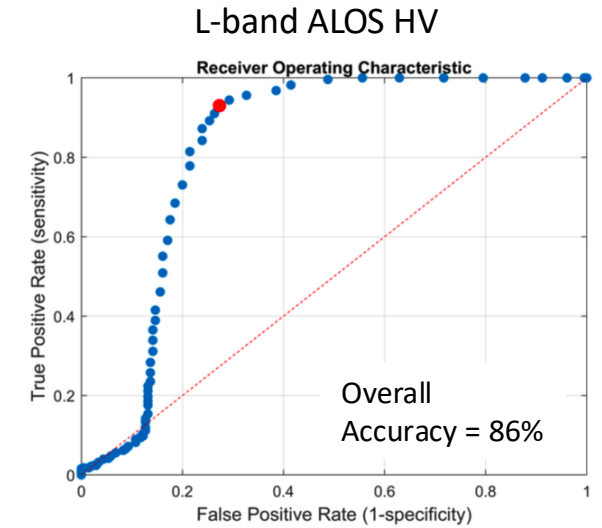
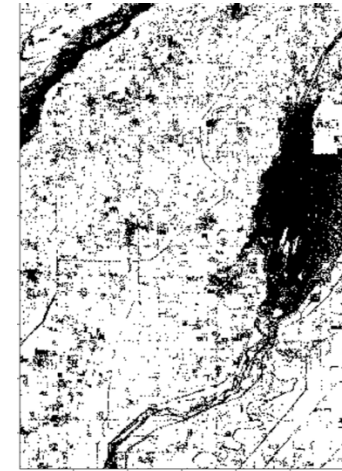
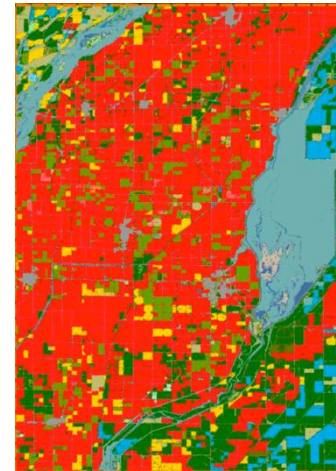
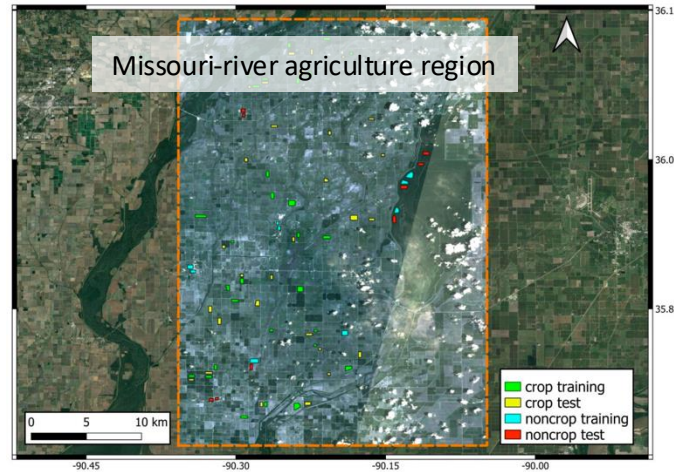


Testing Samples



Classification of Crop Area using PALSAR, Sentinel-1, and Planet Data for the NISAR Mission

G. Anconitano, S. Kim, B. Chapman, J. Martinez, P. Siqueira and N. Pierdicca

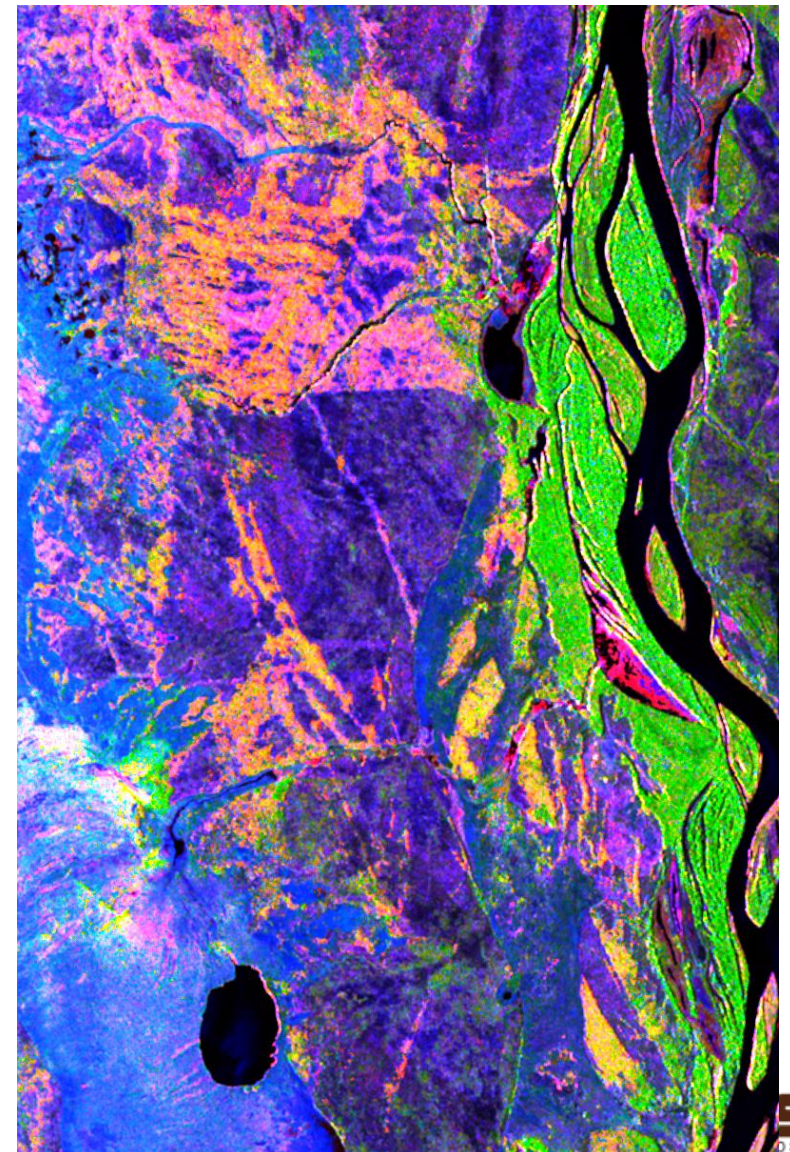
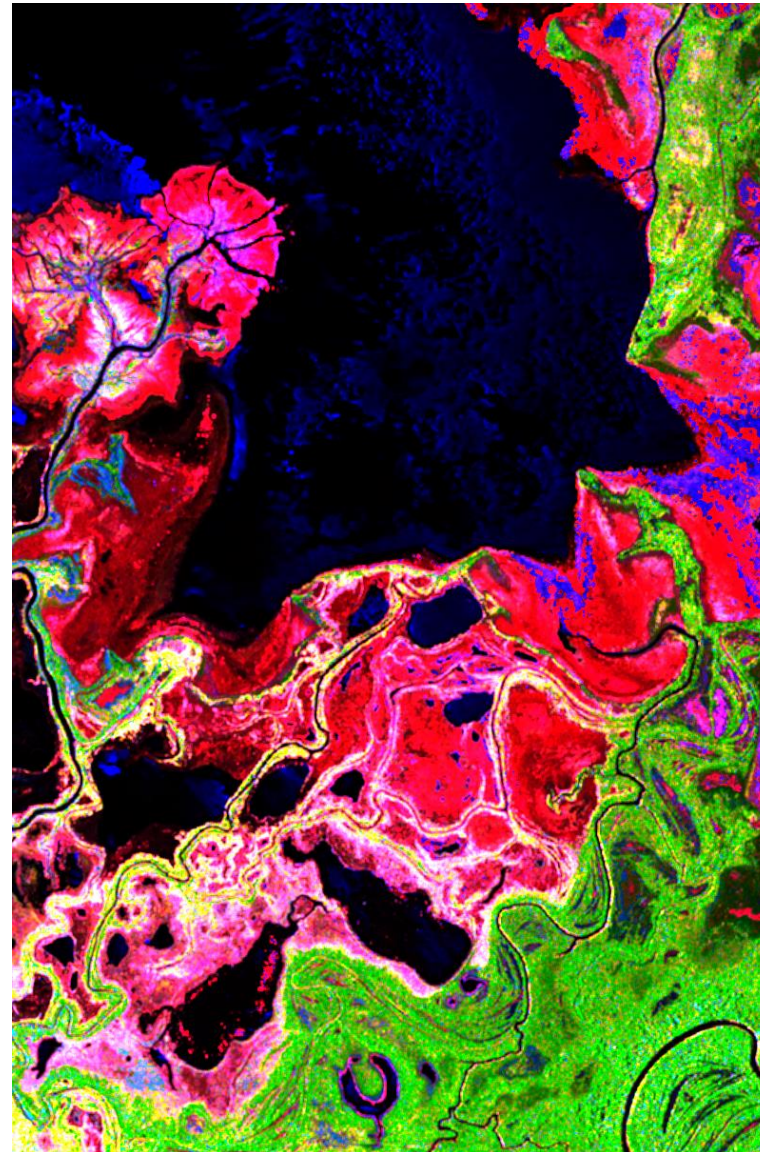
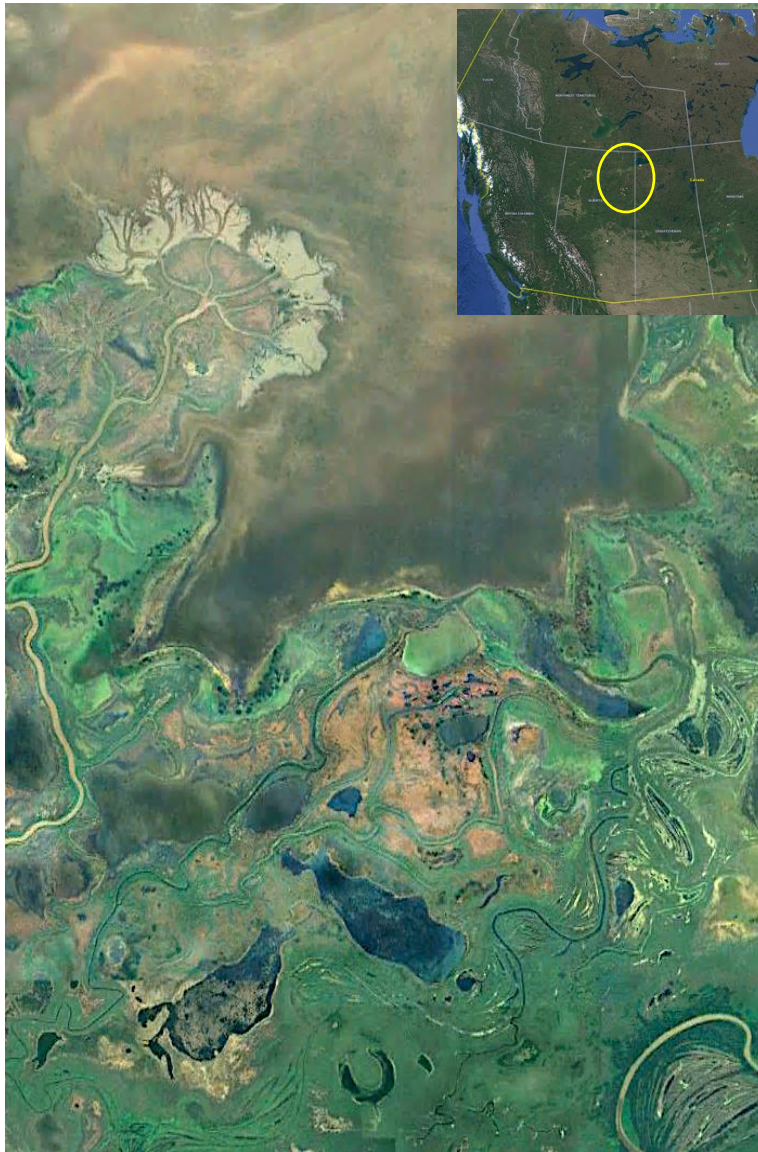


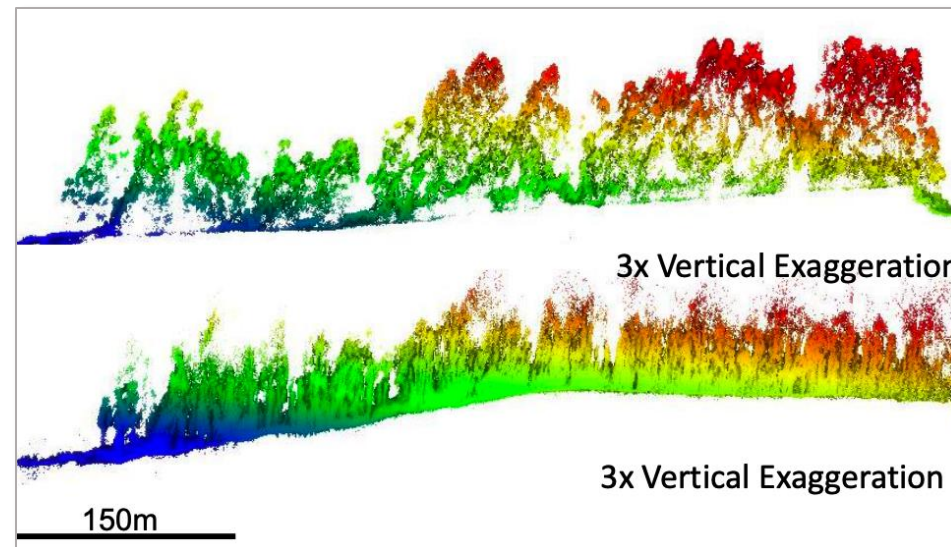
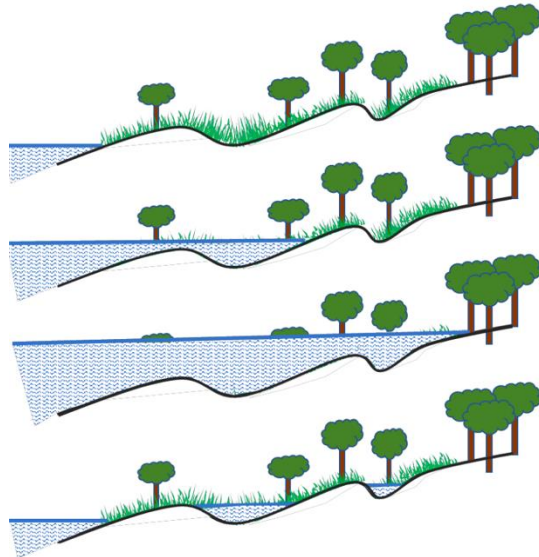
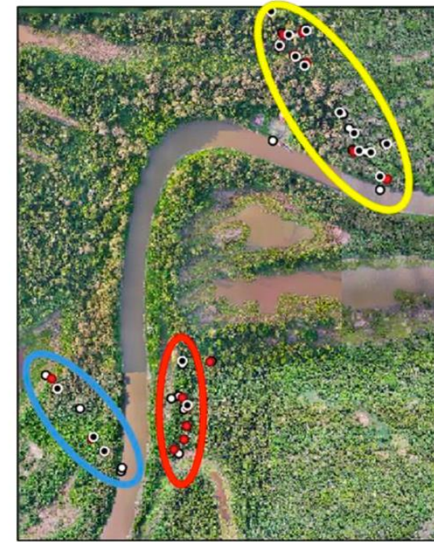
Prototype testing
CoV NDVI &
windshield
survey for
crop/non-crop



Wetlands: Peace-Athabasca Delta, Alberta

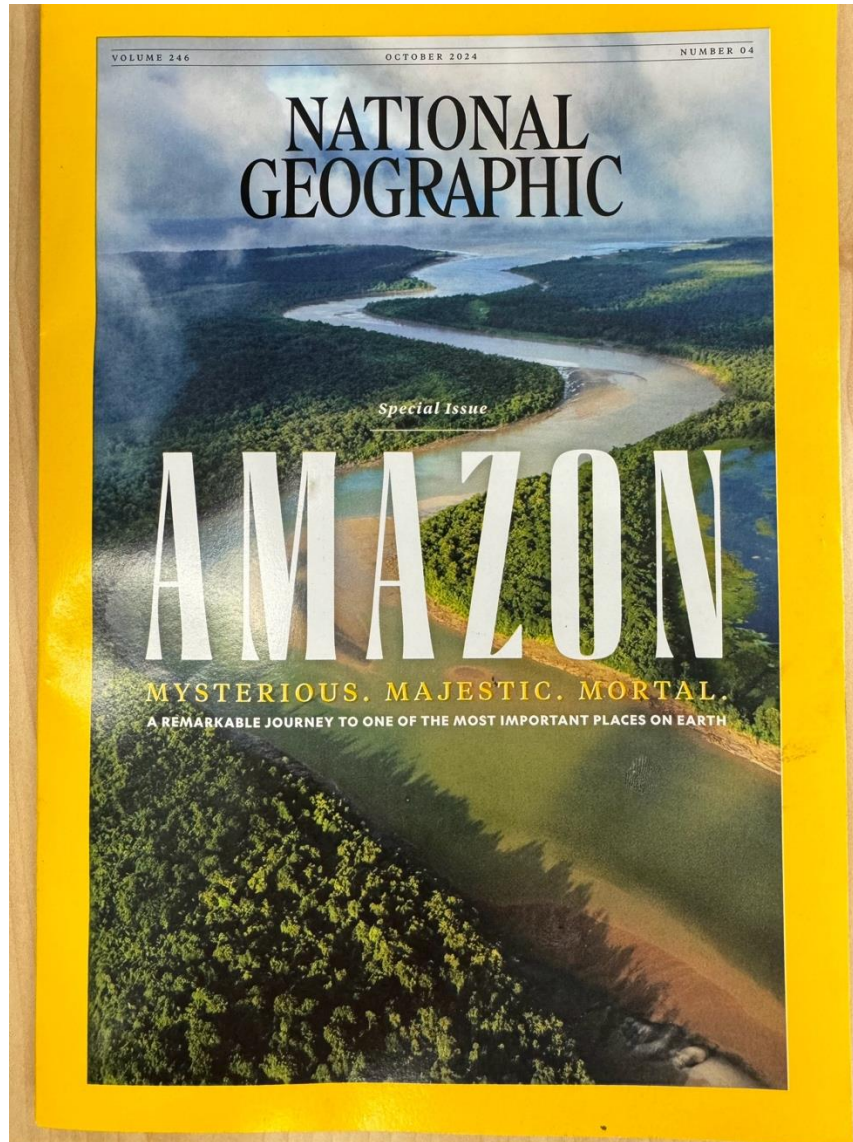
Scattering Mechanisms (**double-bounce**, **volume**, **surface**)



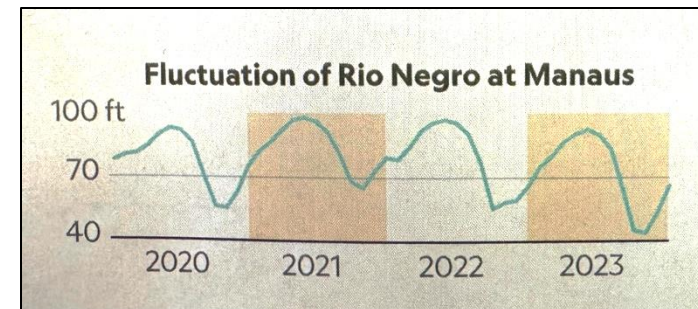




Wetlands Highlights Pacaya Samiria

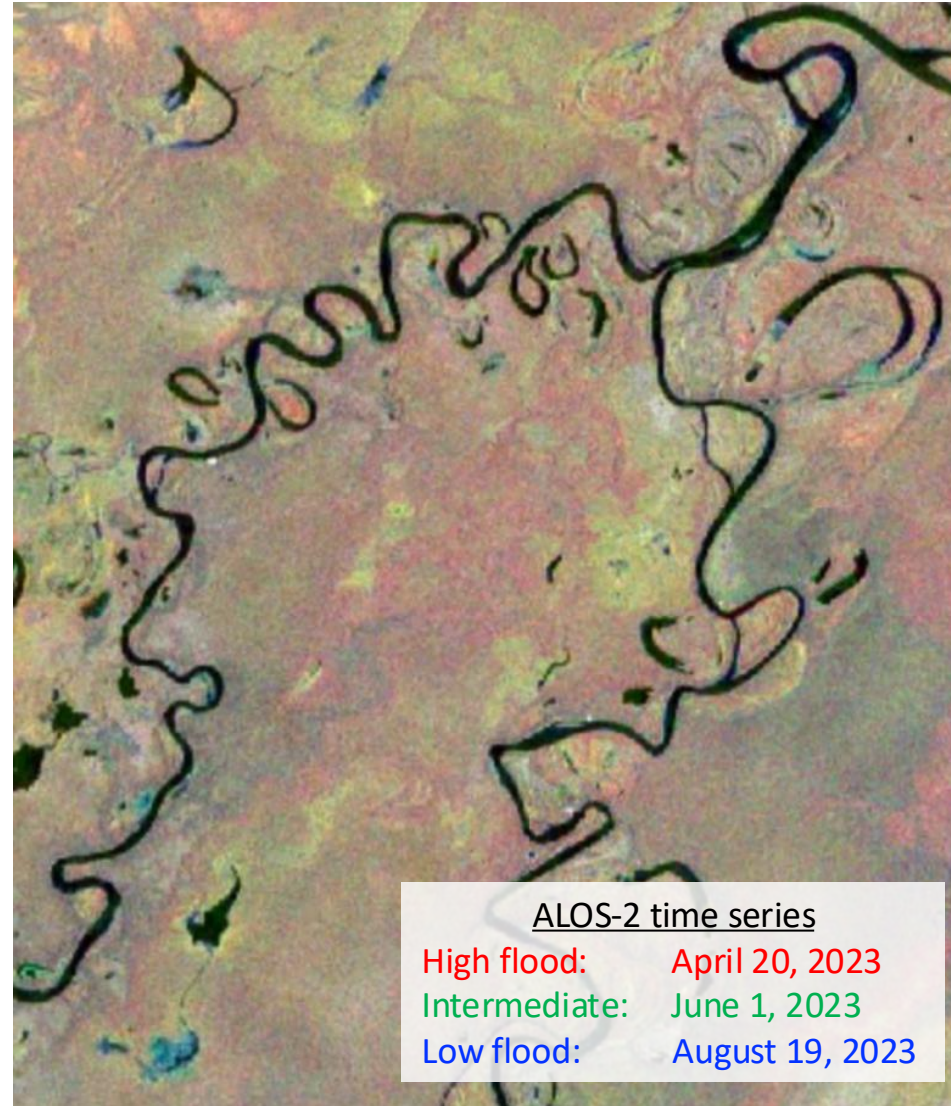


Thiago Sanna Freire Silva w/”terrestrial” lidar





Wetlands Highlights Pacaya Samiria



ALOS-2 time series

High flood: April 20, 2023
Intermediate: June 1, 2023
Low flood: August 19, 2023



0 Getting Started

0.1 Overview of the Coefficient of Variation

Python code to implement coefficient of variation (CV) for crop/non-crop classification using a Receiver Operating Characteristic (ROC) curve for a time-series of SAR images. The notebook statistically calculates the CV for a stack of time-series imagery. The CV output is then used to generate a ROC curve by using the USDA Cropland Data Layer (CDL) as ground truth. Pixels classified by the CDL as "Water" are masked and not used in classification because, water has a high variation measurement not comparable to the CV values of other non-cropland land covers and is often misclassified because of this. The statistic Youden's Index is calculated to determine the ideal threshold on the curve to use for best classification results. The accuracy of the classification compared to the CDL as ground truth are calculated for the CV crop/non-crop classification. The classified image is exported as a Geotiff. A CSV file is exported containing accuracy statistics for the classification.

Coefficient of Variation is calculated by: Standard Deviation/Mean

Datasets needed:

Timeseries of SAR imagery

CDL available at <https://nassgeodata.gmu.edu/CropScape/>

0.2 Data Flow Diagram

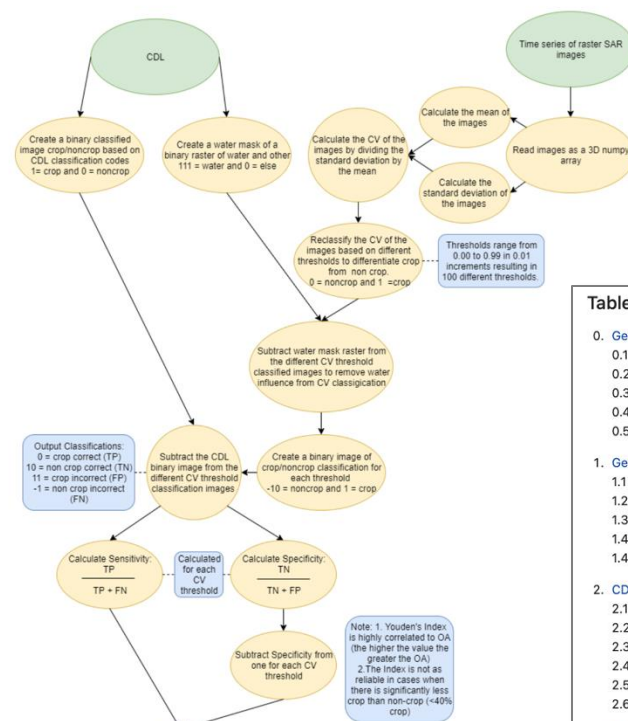


Table of Contents

- Getting Started
 - Overview of the Coefficient of Variation
 - Data Flow Diagram
 - Import Python Modules (code)
 - Set the Input Parameters (code)
 - Set the Output Parameters (code)
- Get Data
 - Pre-Launch: Get GCOV data from S3 Buckets
 - Post-Launch: Query EarthData using earthaccess for GCOV data
 - Post-Launch: Query ASF using asf_search for GCOV data
 - Select Images to Include in Time-Series Stack
 - Get Geocoding Information from First/Reference Images
- CDL Preparation
 - Download the CDL
 - Sample image of the Cropland Data Layer
 - A simple Crop-/Non-Crop mask
 - Identifying Crop pixels in the CDL
 - Image of the Crop-/Non-Crop classification based on the CDL
 - A statistical summary of the number of Crop and Non-Crop pixels from the CDL
- Time-Series analysis of SAR images
 - Read in Imagery

5.2 Display Youden's Index

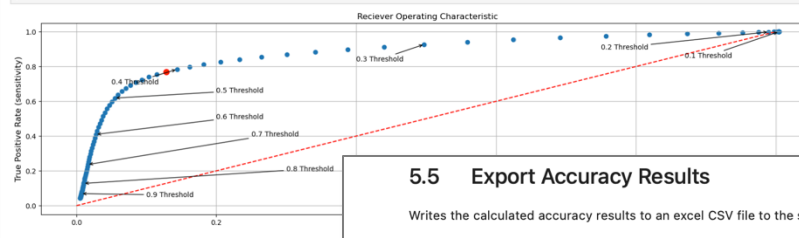
```

x, y = data100.T
plt.scatter(x, y)
plt.plot([0.0, 1.0], [0.0, 1.0], linestyle="--", color="red")
plt.plot([fpr_specificity_ideal], [tpr_sensitivity_ideal], marker="o", markersize=8, color="red")

#arrows highlighting where each threshold value is
plt.annotate('0.1 Threshold', xy=(sub_specificity_x[10], sensitivity_y[10]),arrowprops=dict(arrowstyle='->'), xytext=(0.87, 0.85))
plt.annotate('0.2 Threshold', xy=(sub_specificity_x[20], sensitivity_y[20]),arrowprops=dict(arrowstyle='->'), xytext=(0.75, 0.9))
plt.annotate('0.3 Threshold', xy=(sub_specificity_x[30], sensitivity_y[30]),arrowprops=dict(arrowstyle='->'), xytext=(0.4, 0.83))
plt.annotate('0.4 Threshold', xy=(sub_specificity_x[40], sensitivity_y[40]),arrowprops=dict(arrowstyle='->'), xytext=(0.05, 0.7))
plt.annotate('0.5 Threshold', xy=(sub_specificity_x[50], sensitivity_y[50]),arrowprops=dict(arrowstyle='->'), xytext=(0.2, 0.65))
plt.annotate('0.6 Threshold', xy=(sub_specificity_x[60], sensitivity_y[60]),arrowprops=dict(arrowstyle='->'), xytext=(0.2, 0.5))
plt.annotate('0.7 Threshold', xy=(sub_specificity_x[70], sensitivity_y[70]),arrowprops=dict(arrowstyle='->'), xytext=(0.25, 0.4))
plt.annotate('0.8 Threshold', xy=(sub_specificity_x[80], sensitivity_y[80]),arrowprops=dict(arrowstyle='->'), xytext=(0.3, 0.2))
plt.annotate('0.9 Threshold', xy=(sub_specificity_x[90], sensitivity_y[90]),arrowprops=dict(arrowstyle='->'), xytext=(0.1, 0.05))

#Setting plot layout
plt.grid()
plt.title('Receiver Operating Characteristic')
plt.ylabel('True Positive Rate (sensitivity)', fontsize=12)
plt.xlabel('False Positive Rate (1-specificity)', fontsize=12)
plt.rcParams['figure.figsize'] = (10,10)

plt.show()
  
```



5.5 Export Accuracy Results

Writes the calculated accuracy results to an excel CSV file to the set output directory

```

[118]: CV_classification_binary = "NISAR_L3_CropAreaClassification.tif" #
CV_classification_filename_with_accuracy = "CV_classification_with_Accuracy_results = "NISAR_L3_CropAreaClassification_accuracy_statistics.csv"

[119]:
l0 = [best_thresh]
l1 = [p_overall_correct]
l2 = [p_crop_correct]
l3 = [p_non_correct]
l4 = [p_crop_incorrect]
l5 = [p_non_incorrect]
l6 = [crop_p_accuracy]
l7 = [non_p_accuracy]
l8 = [crop_u_accuracy]
l9 = [non_u_accuracy]
l10 = [Kappa_coefficient]
l11 = [j_statistic]
l12 = [AUC]

df = pd.DataFrame({"Threshold": l0, "Overall Correct": l1, "% crop correct": l2, "% non-crop correct": l3, "% crop incorrect": l4, "% non-crop incorrect": l5, "% Crop Producers Accuracy": l6, "% Non-crop Producers Accuracy": l7, "% Crop Users Accuracy": l8, "% Non-crop Users Accuracy": l9, "Kappa Coefficient": l10, "J-statistic": l11, "AUC": l12})
df.to_csv(str(aoi_dir / Accuracy_results))

df
  
```

[119]:

Threshold	Overall Correct	% crop correct	% non-crop correct	% crop incorrect	% non-crop incorrect	% Crop Producers Accuracy	% Non-crop Producers Accuracy	% Crop Users Accuracy	% Non-crop Users Accuracy	Kappa Coefficient	J-statistic	AUC	
0	0.38	78.91	25.07	53.84	8.39	11.34	74.91	82.61	68.86	86.51	0.55	0.58	0.85

5.6 Export the Classified Image

Writes the array to a geotiff that is classified by the Youden's index ideal threshold based on CV to the set output directory.

```

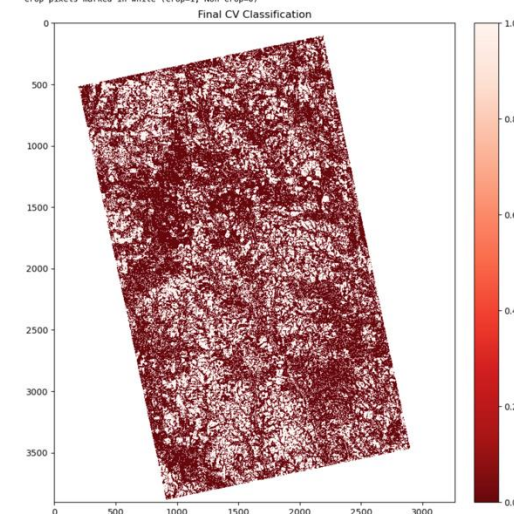
[123]: str(aoi_dir / CV_classification_binary)

[123]: /scratch/alex_eco_test/Little_River_GA/NISAR_L3_CropAreaClassification.tif"

[128]: # Define write_geotiff function - writes an array to a geotiff
def write_geotiff(image, geotrans, cols, rows, spatial_ref, nodata, outfilename):
    driver = gdal.GetDriverByName('GTiff')
    outRaster = driver.Create(outfilename, cols, rows, 1, gdal.GDT_Float32)
    outRaster.SetGeoTransform(geotrans)
    outband = outRaster.GetRasterBand(1)
    outband.WriteArray(image)
    outRasterSRS = sr.SpatialReference()
    outband.SetMetadata('SpatialReference')
    outRasterSRS.ImportFromWkt(spatial_ref)
    outRaster.SetProjection(outRasterSRS.ExportToWkt())
    outband.FlushCache()

write_geotiff_export(CDL_CV_ideal, geotransform, cols, rows, spatial_ref, np.nan, str(aoi_dir / CV_classification_filename_with_accuracy))

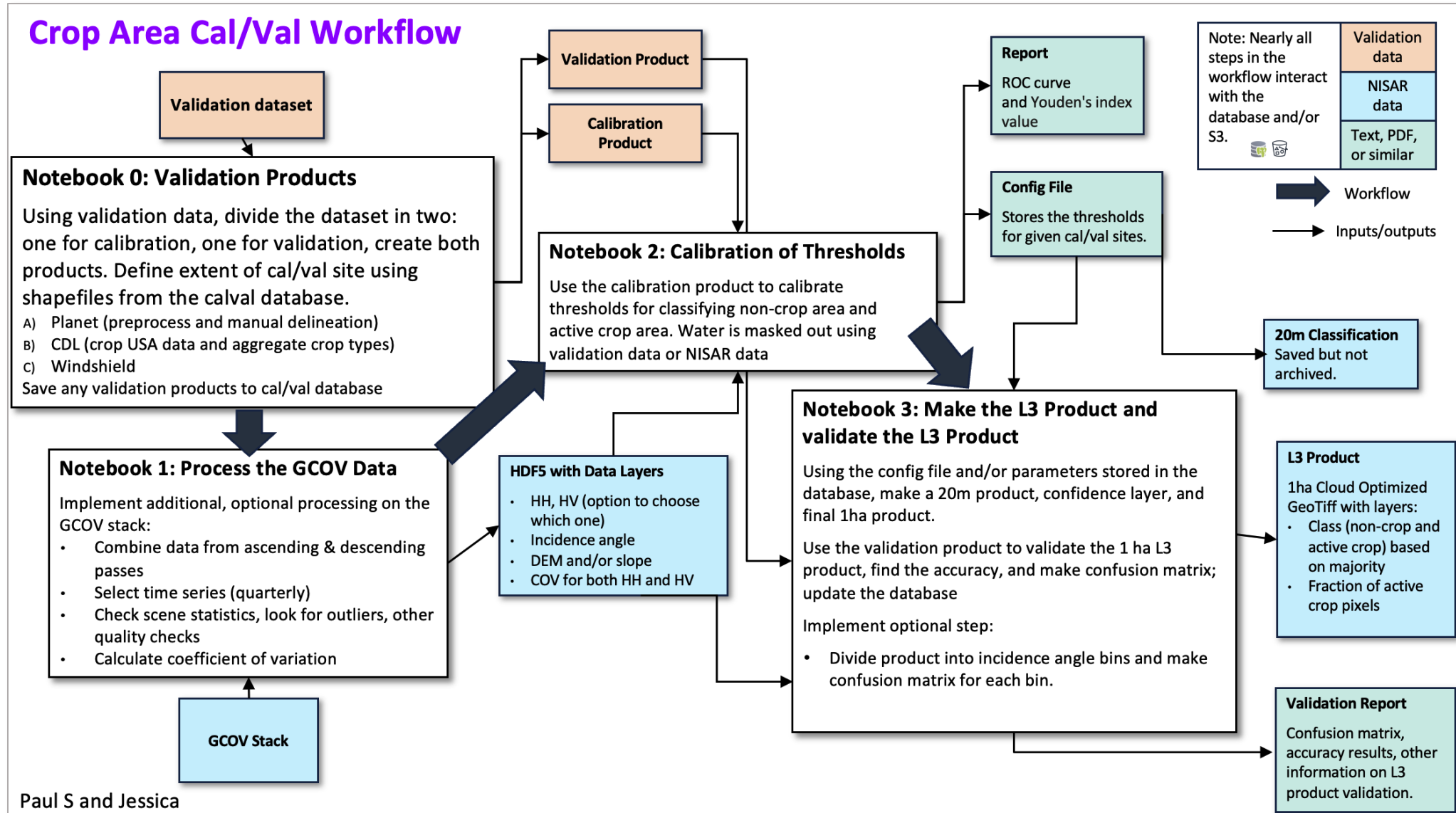
plt.imshow(CV_reclass_ideal, interpolation='nearest', cmap='Reds_r')
plt.colorbar(fraction=0.046*CV_reclass_ideal.shape[0]/CV_reclass_ideal.shape[1], pad=0.04)
plt.title('Final CV Classification')
print('Crop pixels marked in white (Crop=1, Non-Crop=0)')
  
```





On Demand System Workflows

Crop Area Cal/Val Workflow

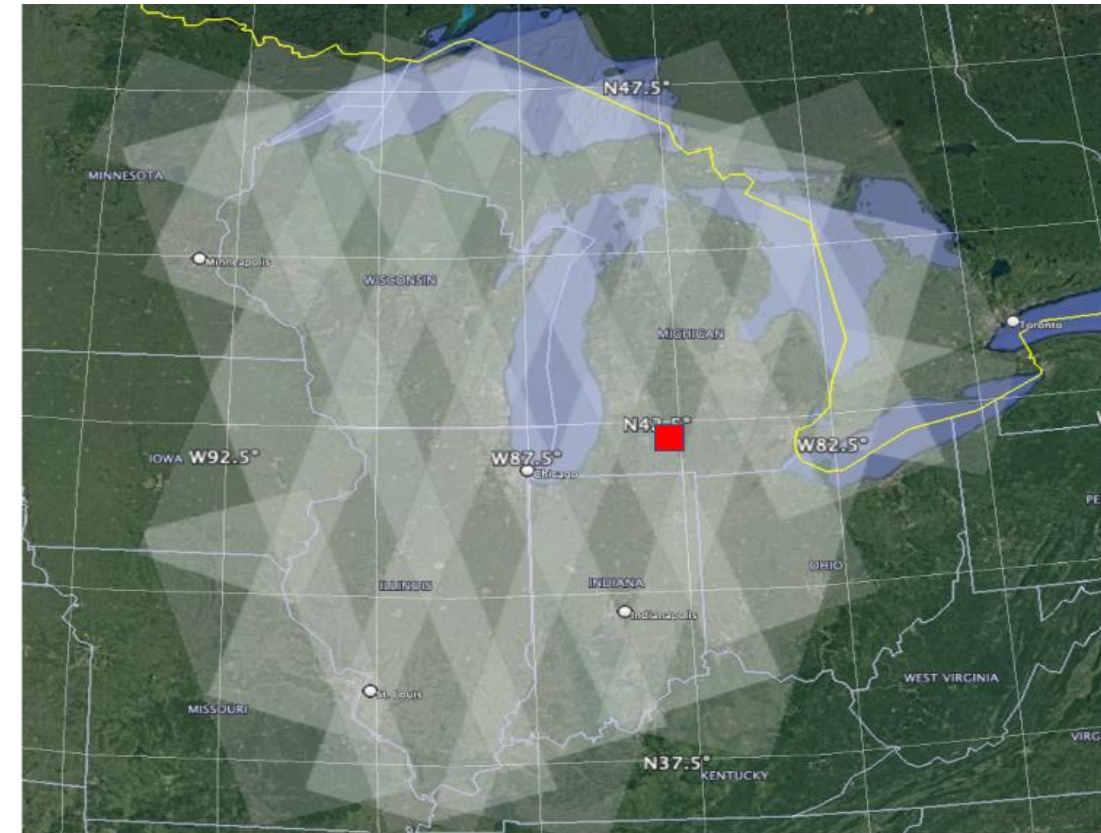
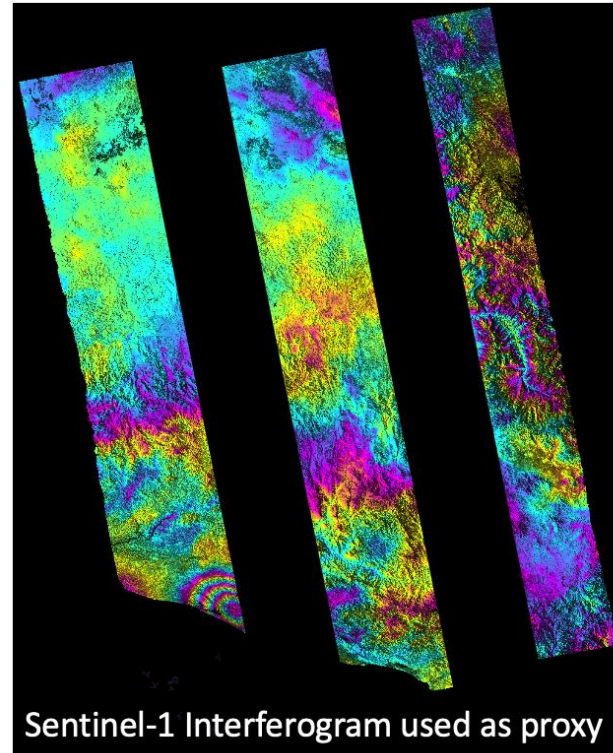
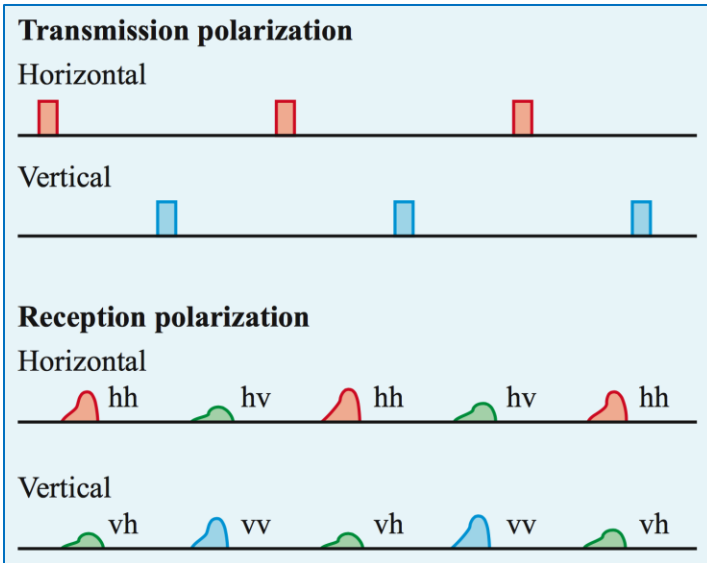


Paul S and Jessica





Things that I am excited about

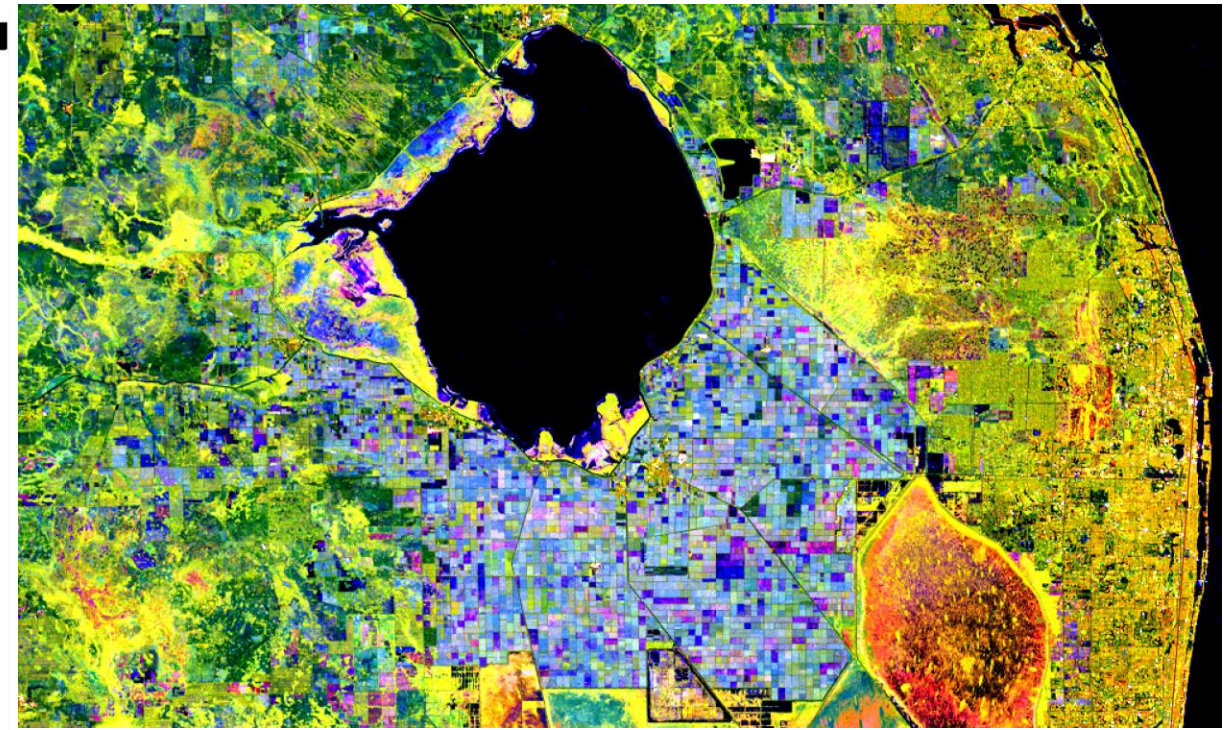
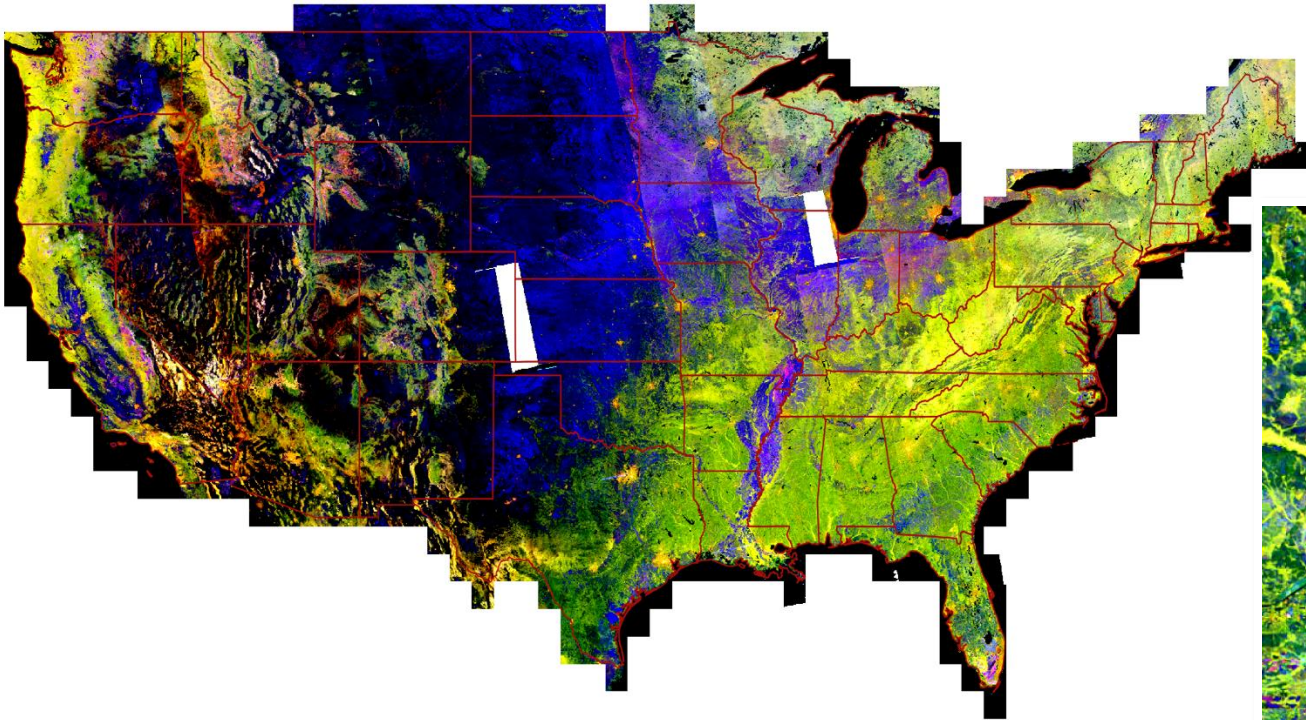


Michigan State Agriculture cal/val site indicated in Red

- Metrics of SAR backscatter over an observation time series (e.g., annual, season) can be used to monitor agricultural activity.

C-VV Median / C-VH Median / C-VH p95-p5

Sentinel-1 2017, Ascending Near over Far Range



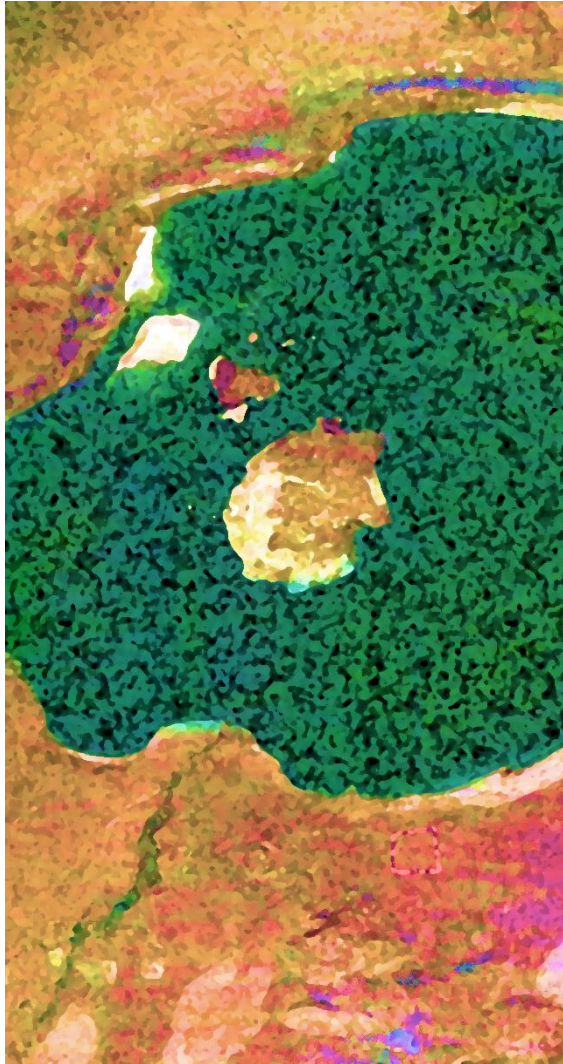
Data Source: ESA/Alaska Satellite Facility
RTC Data Processing: Earth Big Data LLC
Mosaicking and Visualization: Earth Big Data LLC

False color image: $|VV|$, $|HV|$, $|VV/HV|$

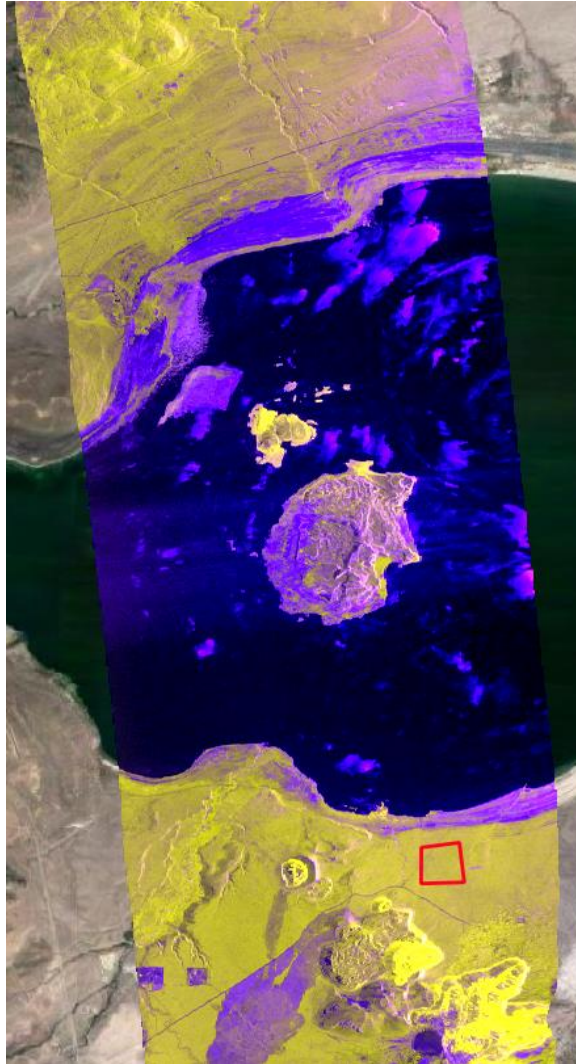
Scale [dB]: (-30 to -10, -35 to -15, 4 to 12)

Multifrequency!

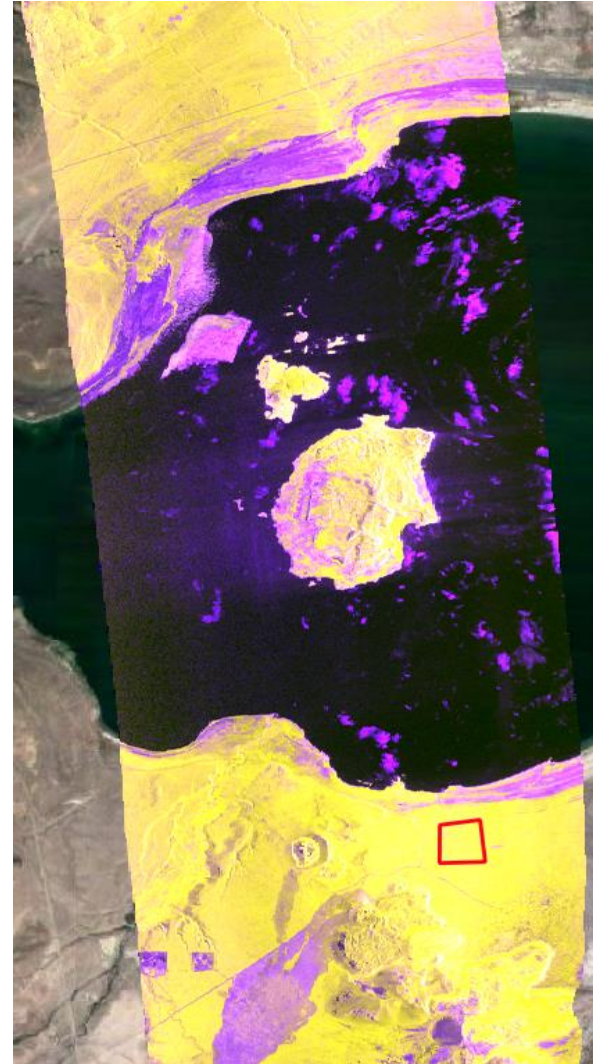
P-band ??



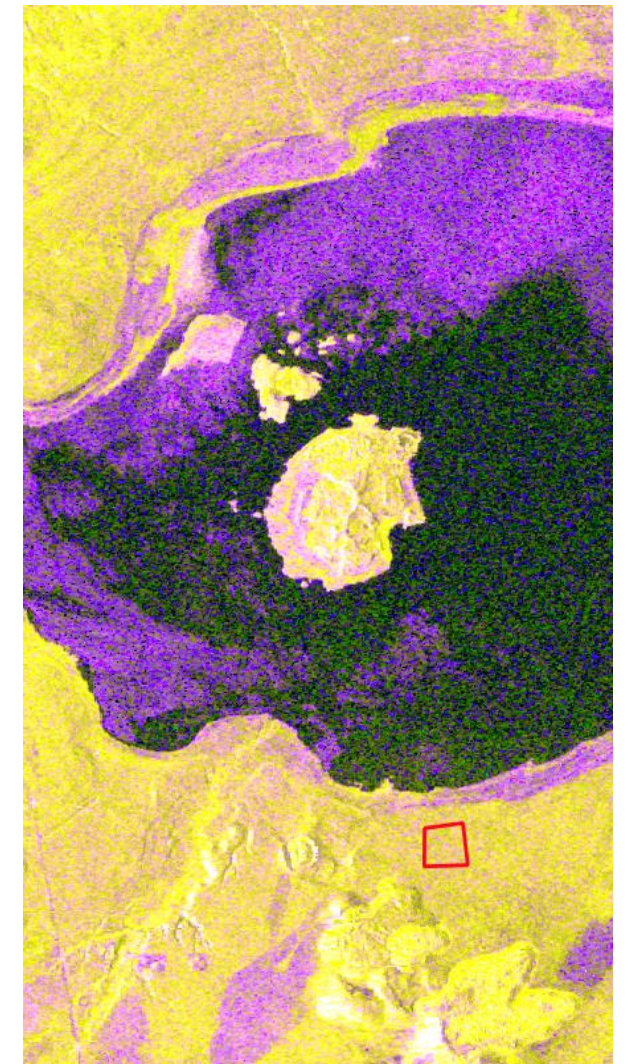
L-band

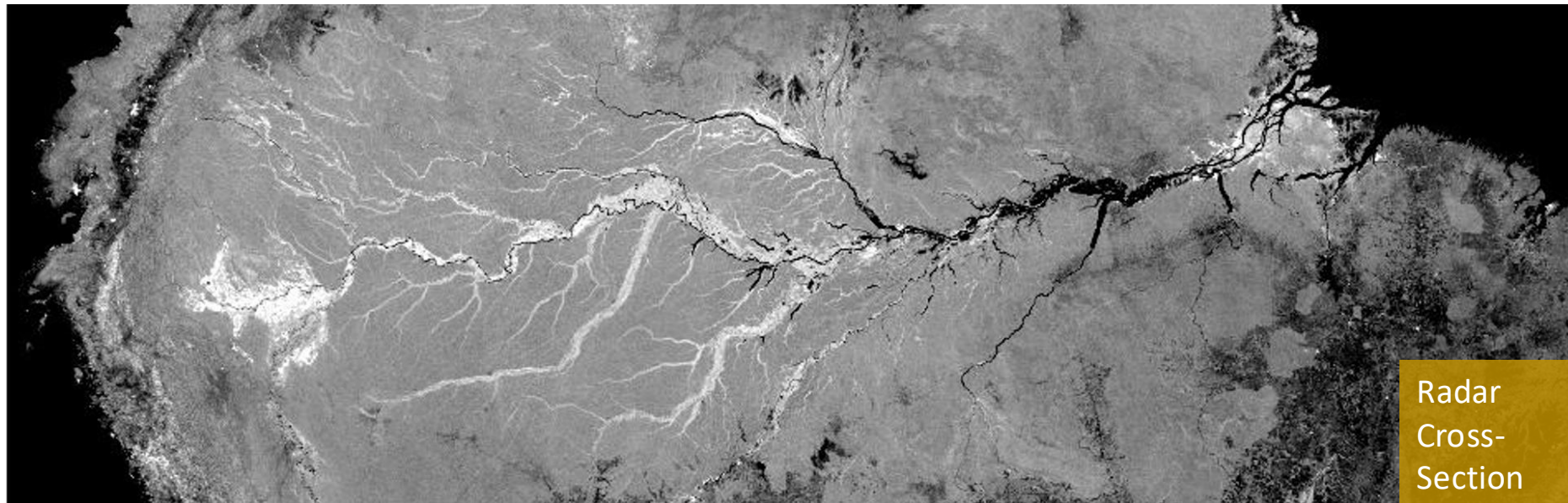
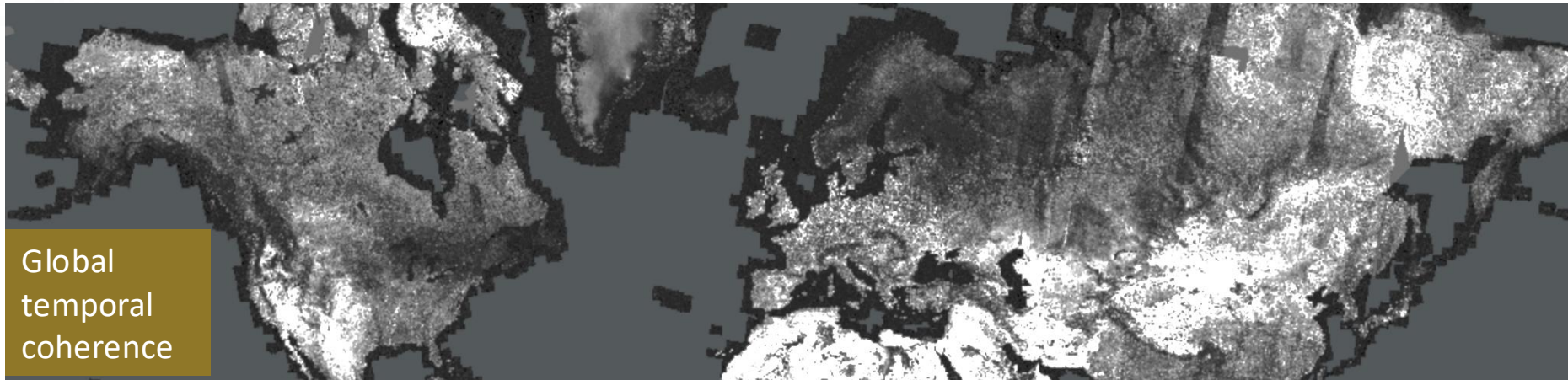


S-band



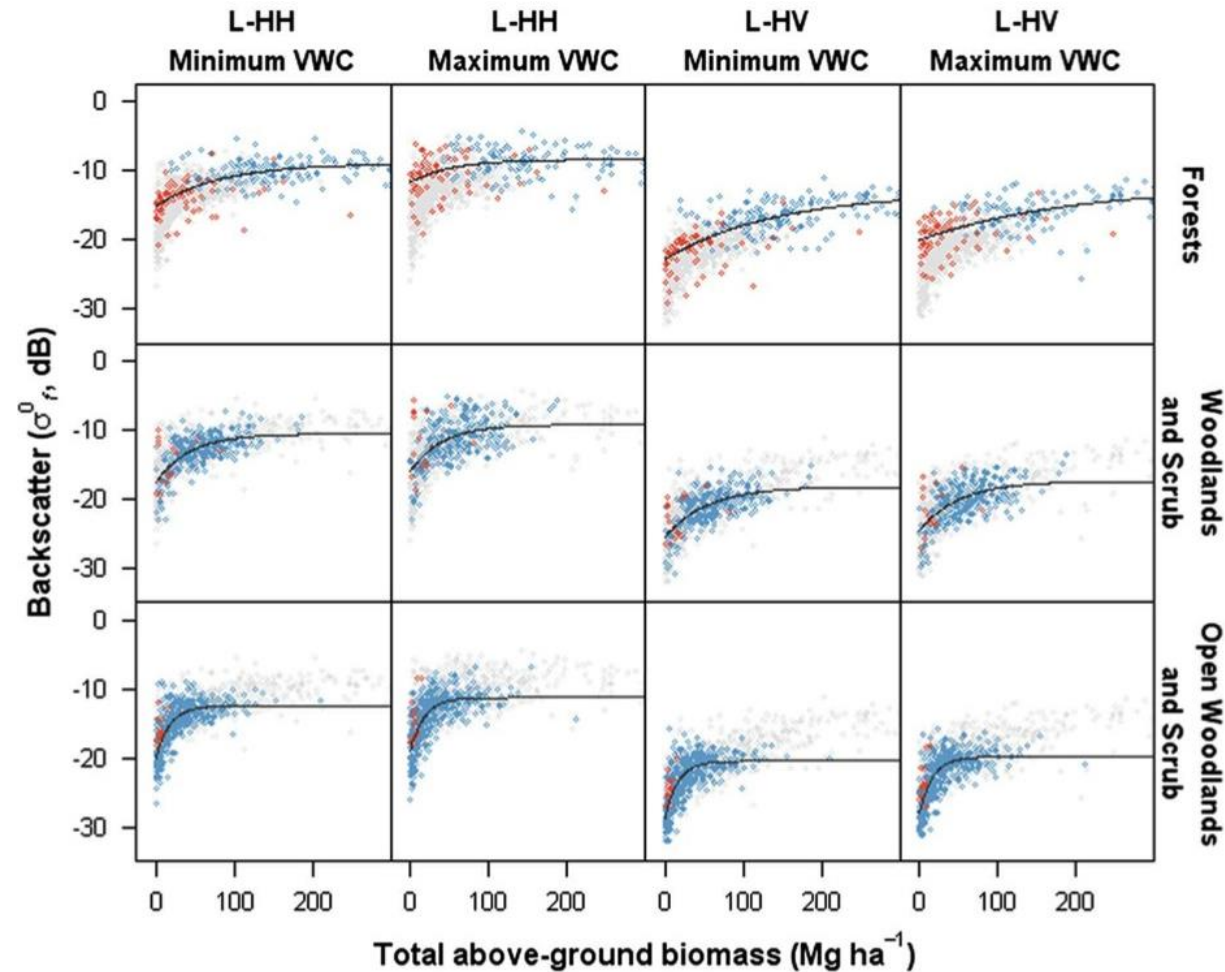
C-band





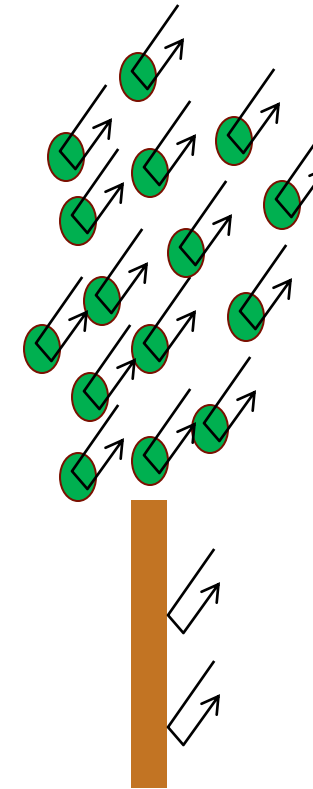
Biomass and Volume Scattering

increased biomass is associated with increased radar power return

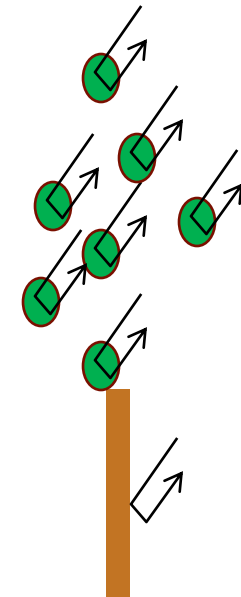


ALOS remnant (blue) and non-remnant (red) biomass relationships in the presence of vegetation water content (VWC) [Lucas et al., JSTARS, 2010]

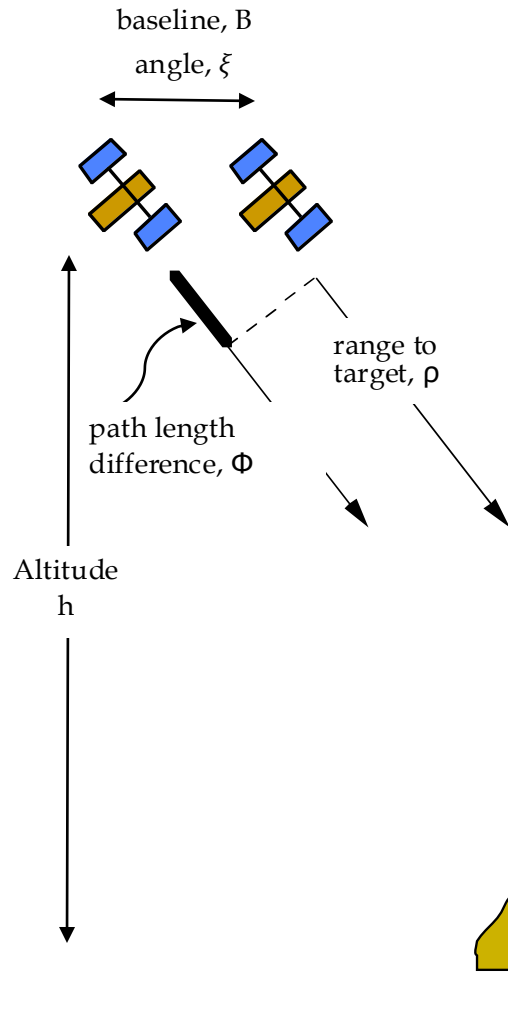
High biomass



Low biomass



- Path length difference can be used to resolve positional ambiguity and determine the height of the terrain.

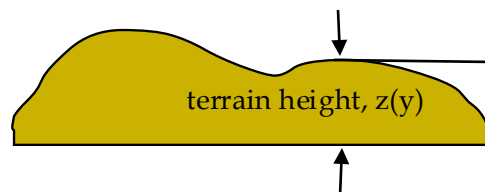


$$z(y) = h - \rho \cos \left(\xi - \sin^{-1} \left(\frac{\lambda \Delta \phi}{4\pi B} \right) \right)$$

$$\gamma = \frac{1}{A\sigma^o} \sum_{i=1}^N \sigma_i e^{-jk_z z_i}$$

$$= \int_{-\infty}^{\infty} \sigma^o(z) e^{-jk_z z} dz$$

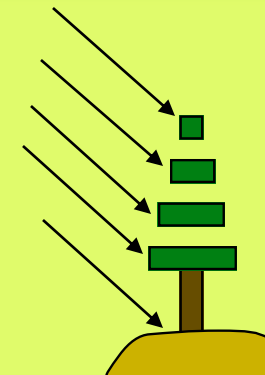
Accuracy is on the order of meters, with a 25m resolution.



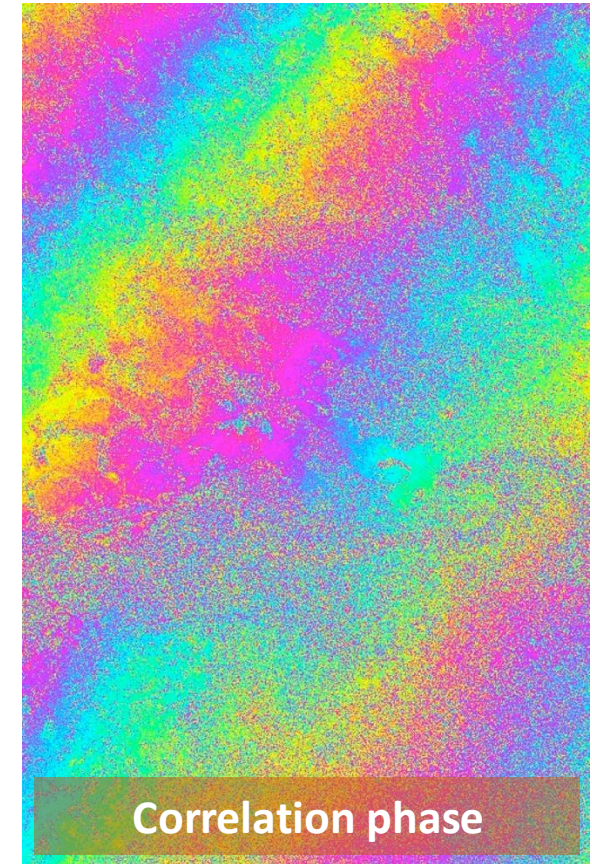
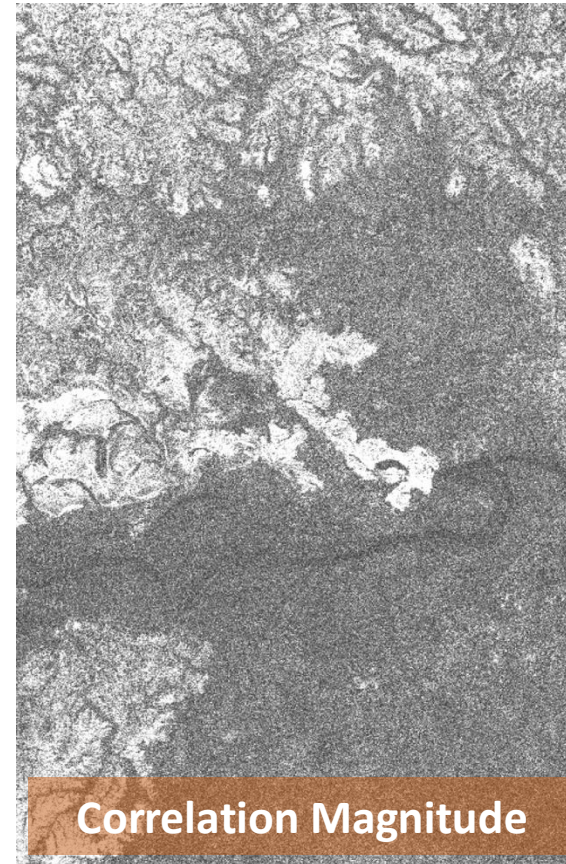
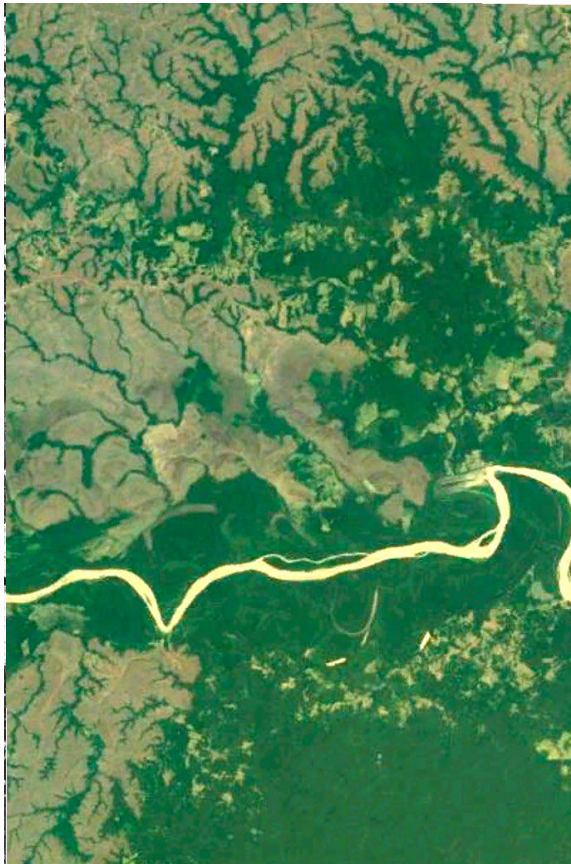
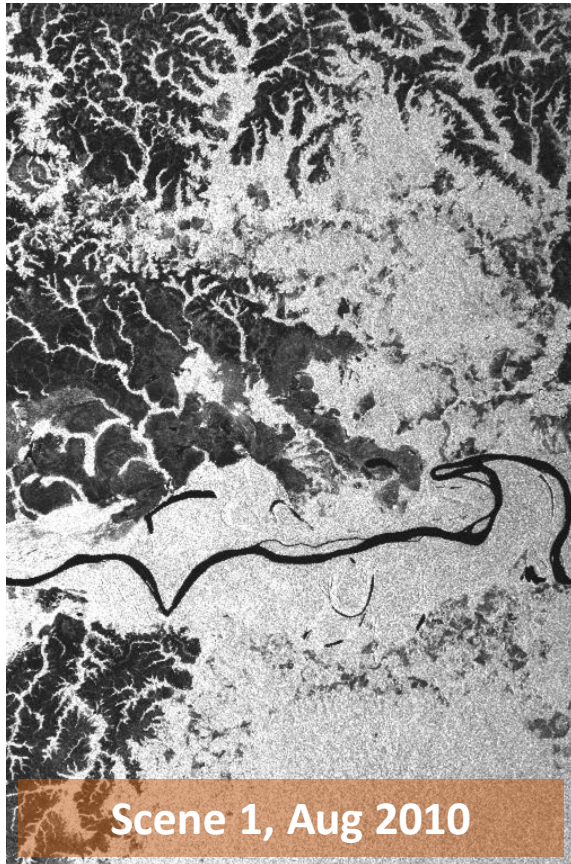
Derivative of interferometric phase with respect to height

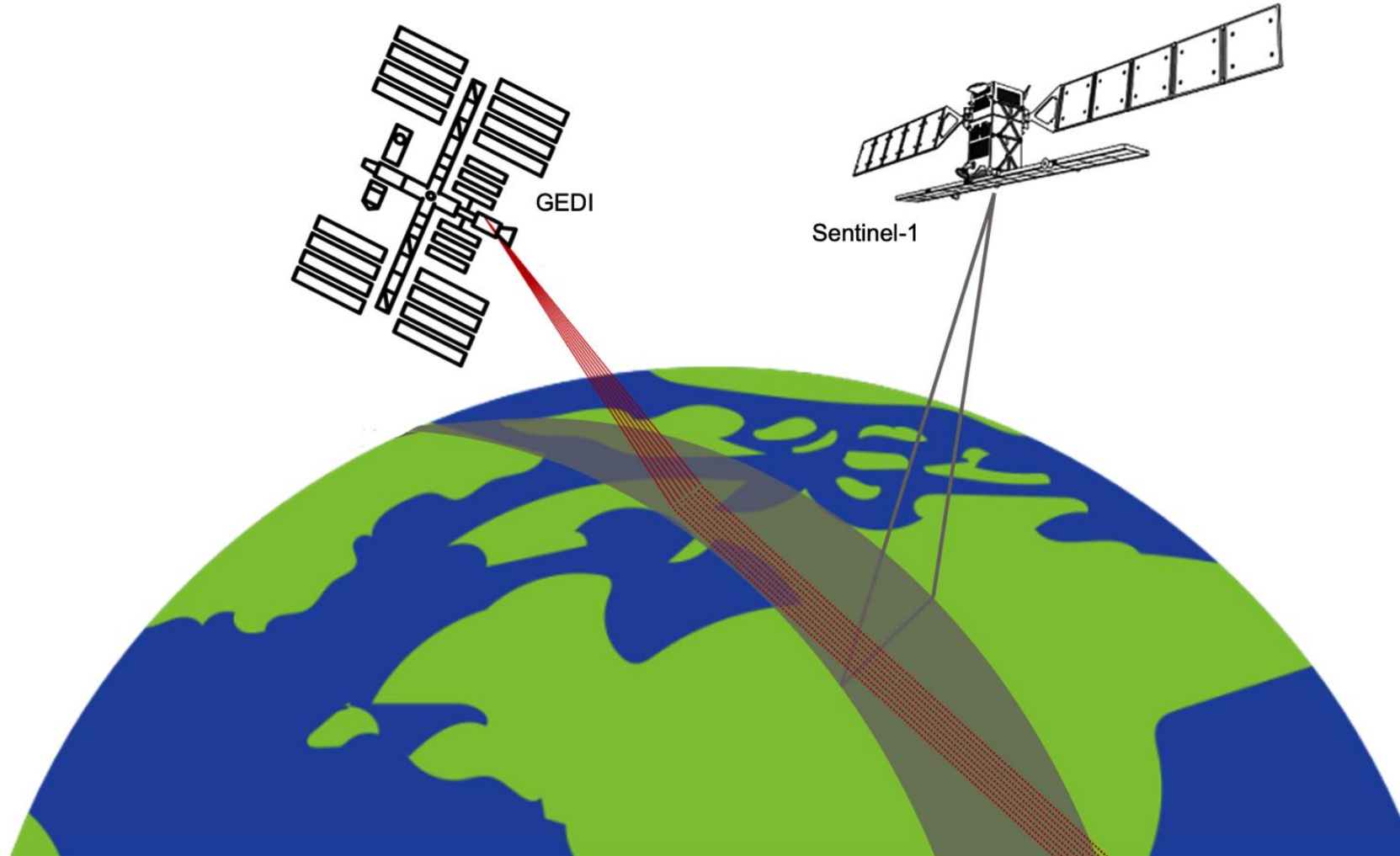
$$k_z = \frac{k_0 B \cos(\theta - \xi)}{\rho \sin \theta}$$

When the signal return comes from multiple heights, a unique signature is observed by the interferometer.



- Interferometry combines two radar scenes to create one, consisting of complex numbers (magnitude and phase)
- Interferometric magnitude is called the "Coherence".
- Interferometric phase is related to the topography







National Aeronautics and Space Administration

NASA **CMS** CARBON MONITORING SYSTEM

Savanna-Bio: Biomass estimation with new spaceborne missions for MRV in Dry Forests and Savannas

John Armston, Laura Duncanson
Mikhail Urbazaev
University of Maryland

Konrad Wessels
Xiaoxuan Li
George Mason University

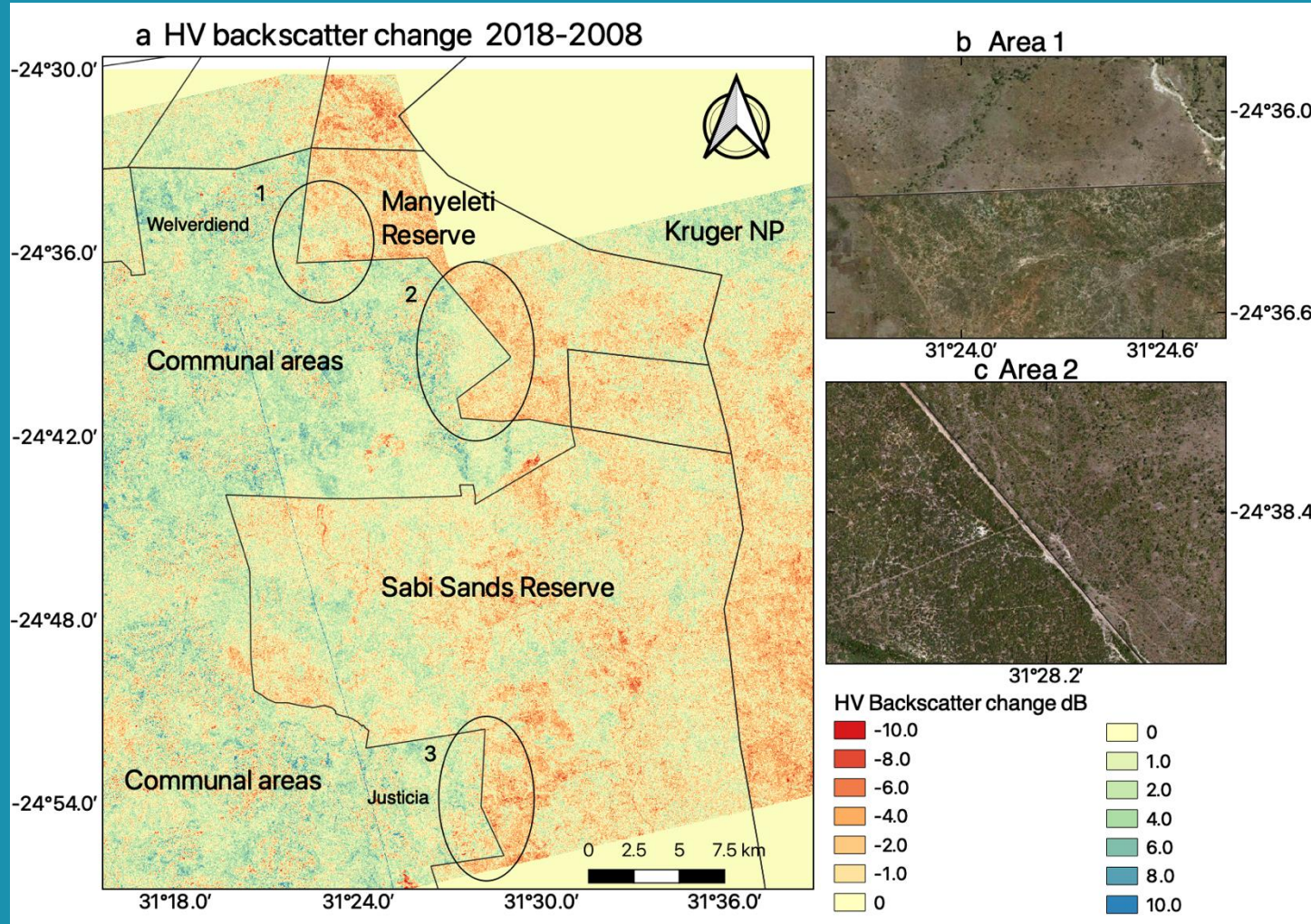
Paul Siqueira
Narayanarao Bhogapurapu
University of Massachusetts

Rajashekar Gopalakrishnan **ISRO, India**
Sean Healey **USFS, USA**
Moses Cho **CSIR, South Africa**
Lungile Moyo & Sindisiwe Mashele **DEFF, South Africa**
Peter Scarth & Stuart Phinn **UQ, Australia**
Daniel Tindall **Qld DESI, Australia**





Disturbance Lowveld, South Africa

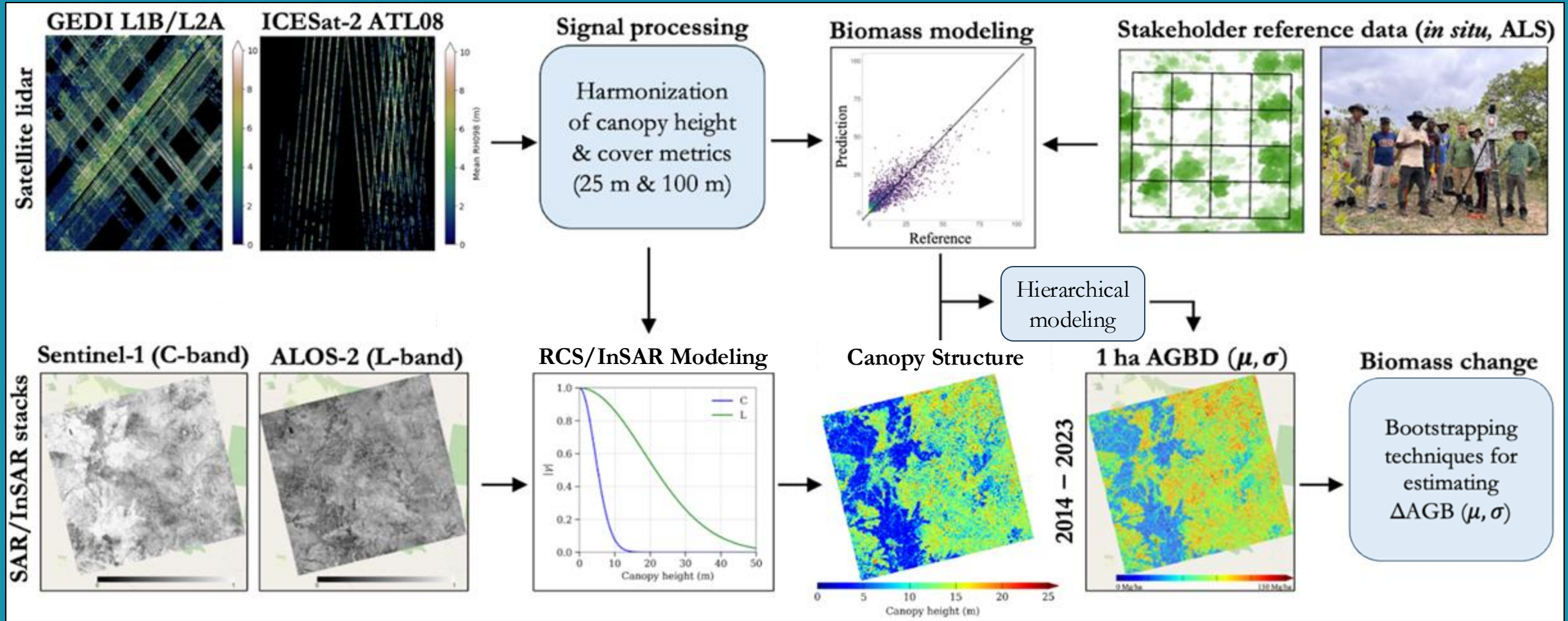


The effects of a fence line on disturbance regimes can clearly be seen in the image

Disturbance likely caused by impact of high elephant numbers and prescribed burns in the conservation areas of the indicated Reserves



OUR APPROACH TO MAPPING SAVANNA ABOVEGROUND BIOMASS AND CHANGE



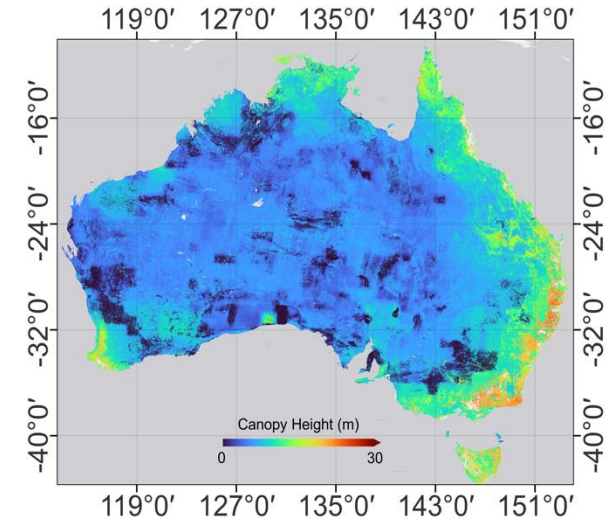
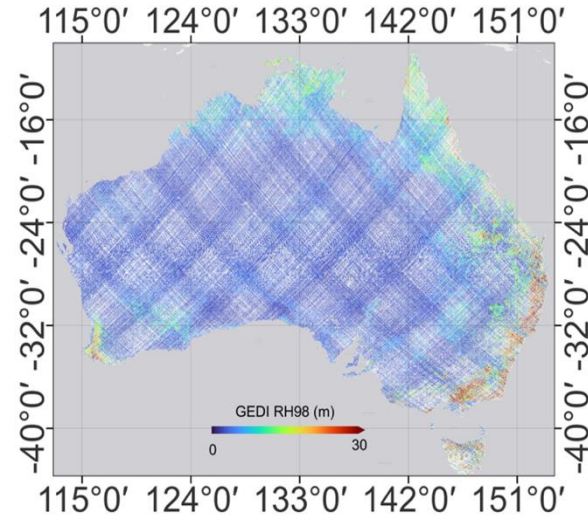
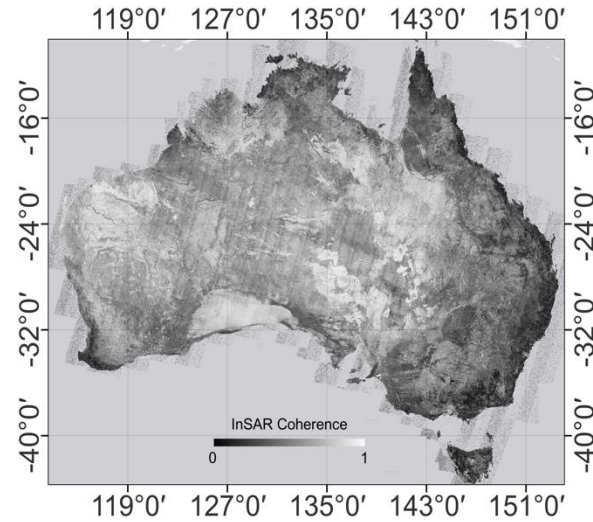
Continental-scale results

S-1 InSAR coherence

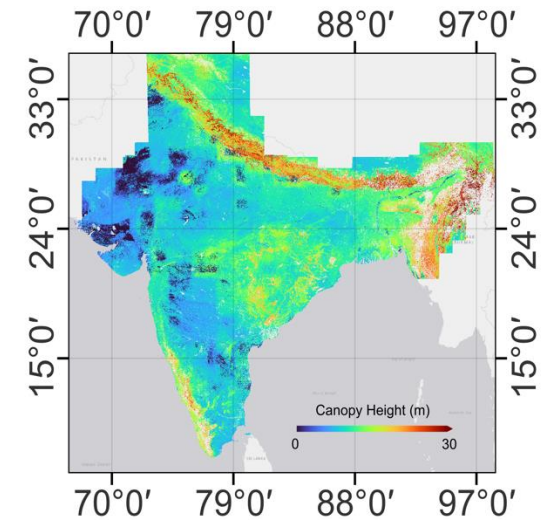
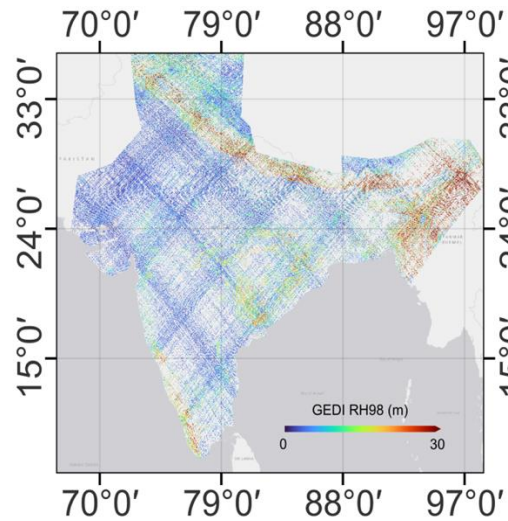
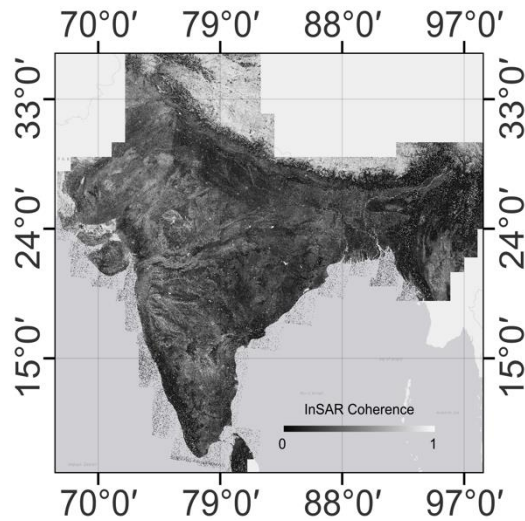
GEDI RH98

Estimated canopy height

Australia



India



Fieldwork in India (Hoshanagabad & Pripiya, MP)



- Dependable L-band time-series (2 observations every 12 days)
 - S-band data over agriculture cal/val sites
- High resolution (~20m),
- Dual-polarized (HH, HV); Quad-pol over India and parts of the US
- Ground-projected data will be co-registered to a fixed grid making time series analysis will be very simple
- Available over all land surfaces, globally
 - will change the way that we use data for Ecosystems
- Downlink data rate is 4.5 TB/day
- Learning how to work with data in the cloud is an important skill to have